



# Representing the front-facing port of Ethernet interfaces

Maxime Chevallier  
*maxime.chevallier@bootlin.com*

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Corrections, suggestions, contributions and translations are welcome!

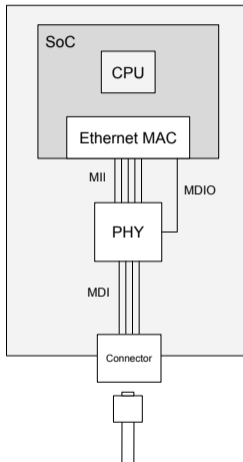




- ▶ Embedded Linux engineer at Bootlin
  - Embedded Linux **expertise**
  - **Development**, consulting and training
  - Strong open-source focus
- ▶ Open-source contributor
- ▶ Living near **Toulouse**, France



# Typical embedded hardware design



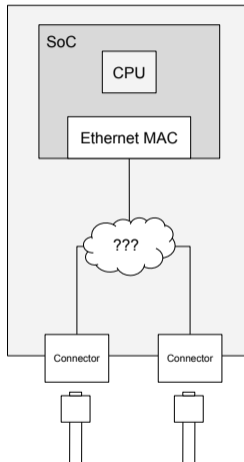
- ▶ MII: Media Independent Interface
  - SGMII, RGMII, RXAUI, etc.
- ▶ MDI: Media Dependent Interface
  - 1000BaseT4, 10BaseT1S, 10GBaseSR, etc.

## Variants

- ▶ The PHY can be integrated in the SoC or MAC
- ▶ The PHY might not exist at all
- ▶ The PHY can be handled by a firmware
- ▶ The Port isn't always BaseT4
- ▶ The Port can be internal (backplane ethernet)



# Mutli-port designs



- ▶ One interface, multiple front-facing ports
- ▶ SFP + Copper combo ports (MCBBin for example)
- ▶ Also used for redundancy



# What do we know about the port ?

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## PHY information

- ▶ `int phydev.port` : `PORT_FIBRE`, `PORT_TP`, etc. Active port.
- ▶ `phydev.supported`, `phydev.advertising` : Supported ports and linkmodes
- ▶ `ethtool_ksettings` : whole NIC (MAC + PHY) supported modes
- ▶ Works well, but only makes sense for a single port.

## SFP/SFF

- ▶ *upstream* MAC or PHY knows precisely the SFP cage protocols
- ▶ When the module is inserted, we detect the real link modes



## New representation

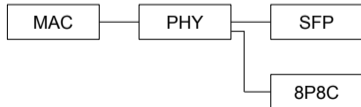
- ▶ struct phy\_port (or struct phy\_mdi ? struct mdi ?)
- ▶ Set of ops to get the status and support using ethtool\_ksettings
  - phy\_port\_ethtool\_ksettings\_[g|s]et
- ▶ Set of ops to configure the port :
  - enabled
  - preferred ?
- ▶ Port "provider" implement these ops : PHY driver, phylink, MAC, SFP
- ▶ Helpers in phylib to make it as transparent as possible



- ▶ Populated by the PHY driver or NIC driver, based on what it knows.
  - Hardcoded, if only one possible mode
  - Reported by HW straps, eeproms or FW (sometimes incorrect)
  - Extracted from devicetree
- ▶ Device Tree current status : Not ideal
  - `ti, fiber-mode, micrel, fiber-mode`
  - `ti, op-mode` : Correlates MII and MDI
  - `max-speed` : (ab)used for 100M limitation ( 2 lanes wired instead of 4)
- ▶ We lack information about the presence or absence of the MDI



# Combo SFP + Copper



```
ethernet-phy@0 {  
    reg = <0>;  
};
```

```
ethernet-phy@0 {  
    reg = <0>;  
    sfp = <&sfp0>;  
};
```

```
ethernet-phy@0 {  
    reg = <0>;  
    sfp = <&sfp0>;  
    // No indication about the 8P8C presence  
};
```





# Devicetree example - WIP

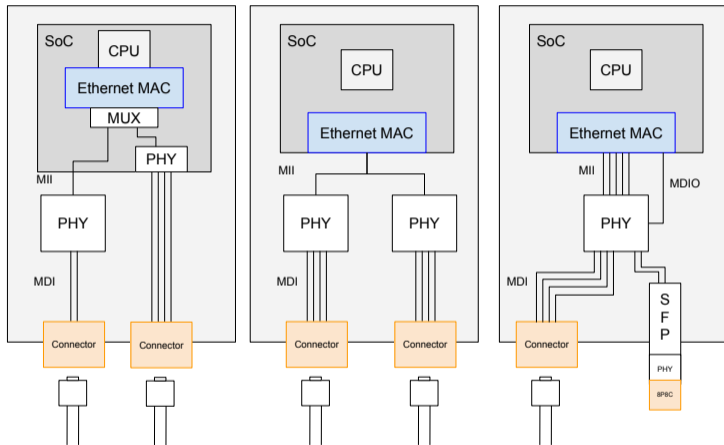
example.dts

```
ethernet-phy@0 {  
    ...  
  
    mdi {  
        port@0 {  
            media = "10baseT", "100baseT", "1000baseT";  
            lanes = <4>;  
  
            /* Attach PSE ports to the actual connector */  
            pses = <&pse_pi0>;  
        };  
  
        port@1 {  
            sfp = <&sfp>;  
            lanes = <1>;  
        };  
    };  
};
```

- ▶ Only relevant when the current representation isn't enough



# Port switching



User cares about which **front-facing-ports** are on a given **interface**



# Link detection and commutation

- ▶ The port's parent must report how link detection happens.
- ▶ Case 1 : We can always independently detect and negotiate the link
  - Dual-PHY with MII multiplexer
  - Support for preferred port
  - Support for highest-speed link
- ▶ Case 2 : While one port is actively used, we can't detect link on other ports
  - Fiber SFP + Copper Combo-PHY
  - Limited support for preferred port
- ▶ Case 3 : We can only detect link one port at a time, even if no port has link
  - Dual-PHY, no multiplexer, PHY has broken isolation
- ▶ Send a gratuitous ARP upon switching port
- ▶ Similarities with `bonding`, but with only one netdev



- ▶ Prototype code using a new set of ethtool netlink messages
  - ETHTOOL\_A\_PORT\_GET
  - ETHTOOL\_A\_PORT\_SET
- ▶ Relies on setting port attributes :
  - enabled : Power the port link detection on/off
  - forced : Force this port to be used.
  - preferred : Prefer this port, if possible



# Conclusion

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## Open questions :

- ▶ Naming : mdi ? port ? something else ?
- ▶ Device tree binding
- ▶ uAPI
- ▶ Integration with bonding ?

## Ongoing work :

- ▶ Support for multiple PHYs started :phy\_link\_topology
- ▶ Support for PHY isolation submitted
- ▶ Next : Port representation and multiplexing
- ▶ PSE integration, with Köry Maincent

# Questions? Suggestions? Comments?

Maxime Chevallier  
*maxime.chevallier@bootlin.com*

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<https://bootlin.com/pub/conferences/2024/lpc/multi-port.pdf>