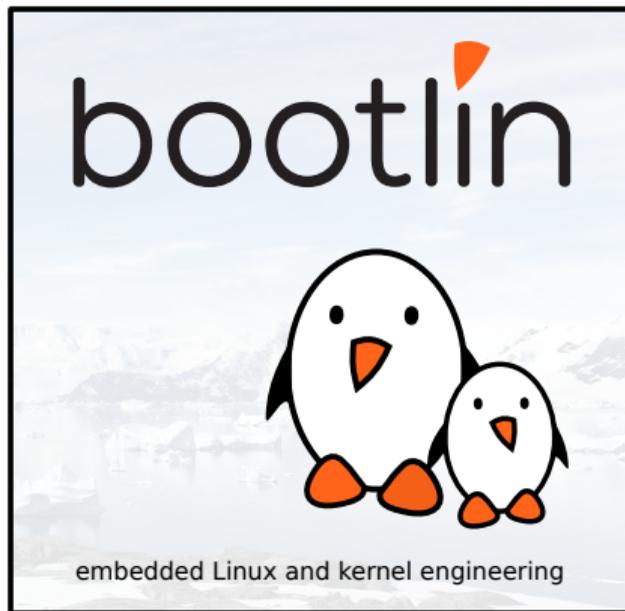




## An introduction to the Linux DRM subsystem

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Corrections, suggestions, contributions and translations are welcome!





- ▶ Embedded Linux engineer and trainer at Bootlin
  - ▶ Embedded Linux **development**: kernel and driver development, system integration, boot time and power consumption optimization, consulting, etc.
  - ▶ Embedded Linux **training**, Linux driver development training and Android system development training, with materials freely available under a Creative Commons license.
  - ▶ <http://bootlin.com>
- ▶ Contributions
  - ▶ **Co-maintainer for the sunXi SoCs** from Allwinner
  - ▶ Contributor to a couple of other open-source projects, **Buildroot**, **U-Boot**, **Barebox**
- ▶ Living in **Toulouse**, south west of France



## Introduction

A long long time ago, in a galaxy (not so) far, far away

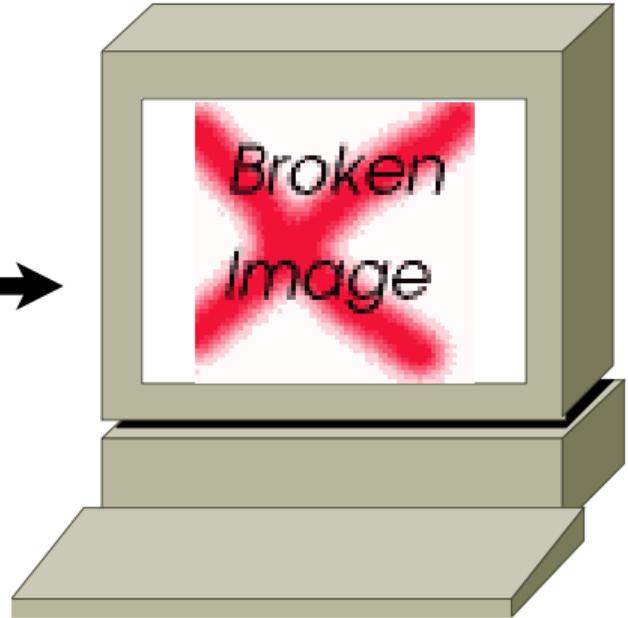
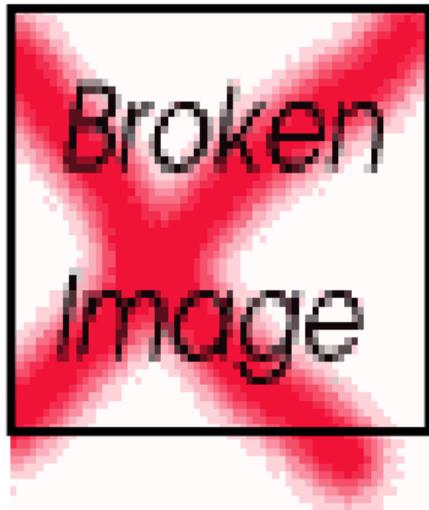


# Framebuffers

- ▶ Display hardware was dead simple...
- ▶ .. and so was the API to drive it.
- ▶ Introducing... fbdev!
- ▶ Allows for three things:
  - ▶ Mode-Setting
  - ▶ Accessing the (only) buffer
  - ▶ Optional 2d acceleration: draw, copy, etc.
  - ▶ And access to the device registers...



# That 90's show



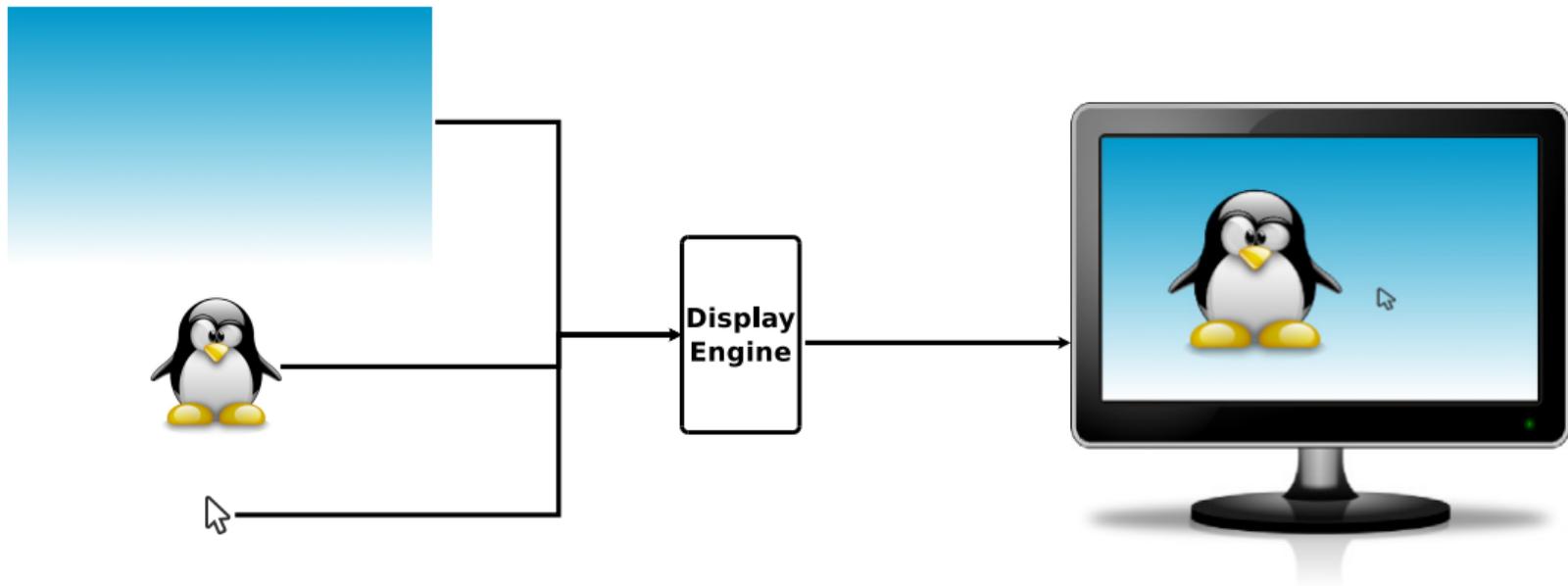


# Back to the future

- ▶ Two different trends
  - ▶ Embedded devices starting to show up, with their low power needs ⇒ Display engines need to accelerate more things
  - ▶ Desktop displays getting more and more fancy in order to play Quake in 4k VR ⇒ Bigger and bigger GPUs
- ▶ Led to two different outcomes:
  - ▶ Interface to drive GPU devices through the kernel: DRM
  - ▶ Hacks piling on in order to fit embedded use-cases: omapdss, pxafb

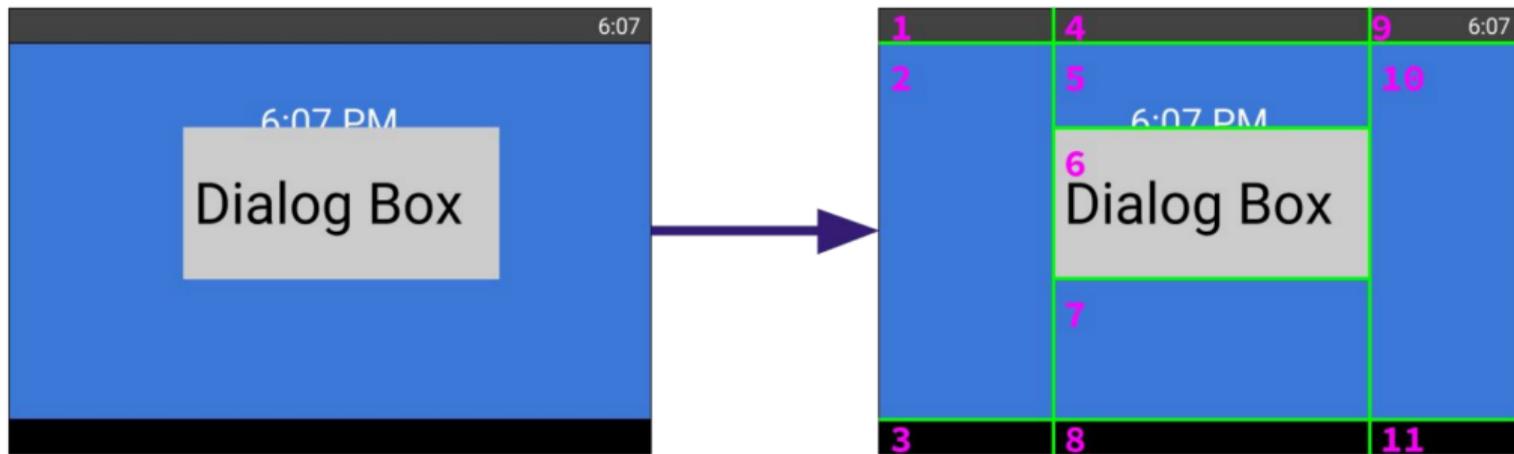


# Composition Evolved





# The droid you're looking at



Sean Paul and Zach Reizner - Google - XDC2016



# Can I talk to the manager?

- ▶ DRM was initially introduced to deal with the GPU's need
  - ▶ Initialize the card, load its firmware, etc.
  - ▶ Share the GPU command queue between multiple applications
  - ▶ Manage the memory (allocation, access)
  - ▶ But not modesetting!
- ▶ All the modesetting was in the userspace, especially in X
- ▶ Race between rendering and modesetting
- ▶ Only one graphical application that needed to remain there all the time
- ▶ (Lack of) Abstraction!
- ▶ Introduction of the Kernel Mode-Setting (KMS) to move the modesetting back into the kernel



# Kill it with fire!

- ▶ Now, fbdev could be implemented on top of KMS...
- ▶ ... Or removed entirely
- ▶ Call for deprecation in 2012 (Hi Laurent!)
- ▶ Last fbdev driver merged in 2014
- ▶ First ARM DRM driver: exynos in 2011
- ▶ Followed: arm, armada, atmel-hclcdc, fsl-dcu, hisilicon, imx, mediatek, meson, msm, mxsfb, omapdrm, pl111, rcar-du, rockchip, shmobile, sti, stm, sun4i, tegra, tve200, etc...



## Two nodes to go please

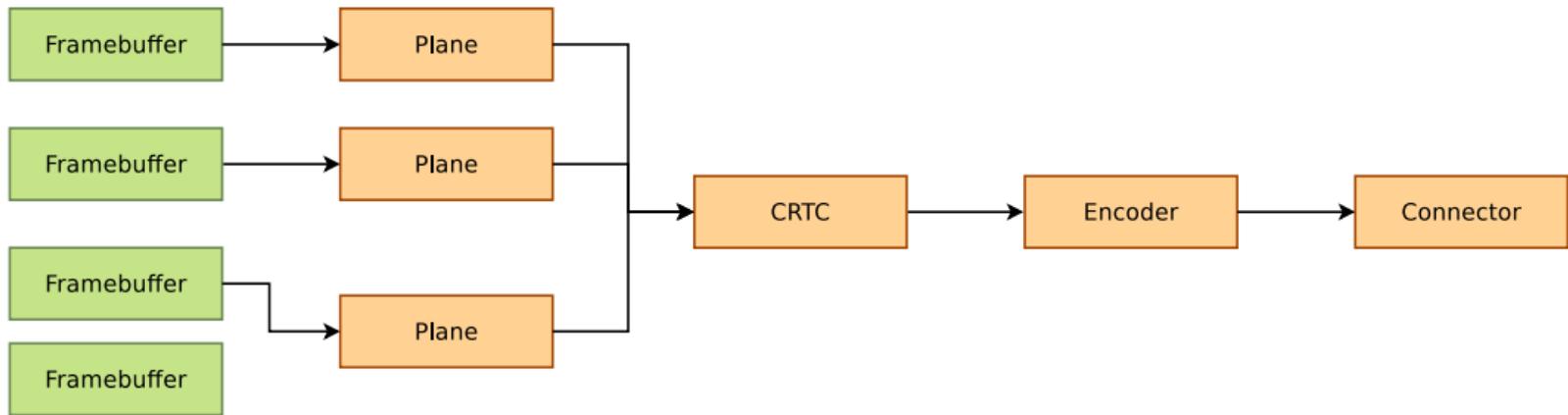
- ▶ Initially, DRM was created for devices that were both displaying and rendering (your traditional PC graphics card).
- ▶ On embedded devices, it's never really been like that
  - ▶ the GPU is discrete and comes from a third party
  - ▶ the display engine is usually designed by the SoC vendor
- ▶ DRM and KMS APIs requiring the same level of privilege, with one master, and were both exposed on the same device file
- ▶ Creation of render nodes
- ▶ Also useful for things like GPGPU, off-screen rendering, more flexible access control



## DRM/KMS



# The pixels must flow



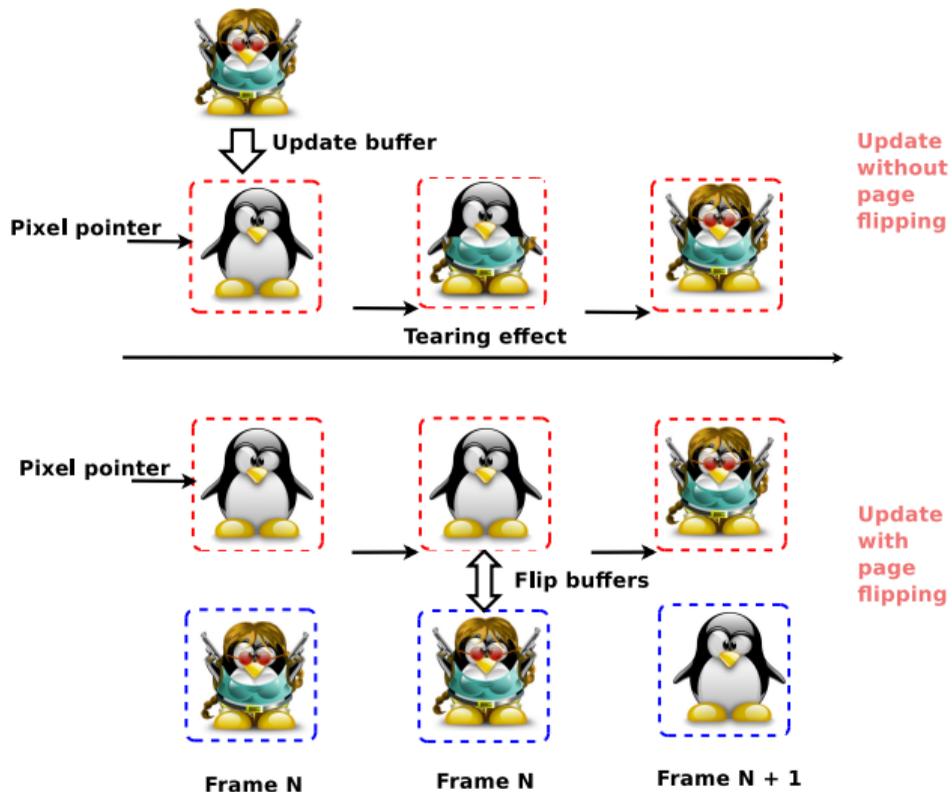


# KMS components

- ▶ Planes
  - ▶ Image source
  - ▶ Associated with one (or more!) framebuffers
  - ▶ Holds a resized / cropped version of that framebuffer



# Page flipping





# KMS components

- ▶ Planes
  - ▶ Image source
  - ▶ Associated with one (or more!) framebuffers
  - ▶ Holds a resized / cropped version of that framebuffer
- ▶ CRTCs
  - ▶ Take the planes, and does the composition
  - ▶ Contains the display mode and parameters



# KMS components

- ▶ Planes
  - ▶ Image source
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- ▶ CRTCs
  - ▶ Take the planes, and does the composition
  - ▶ Contains the display mode and parameters
- ▶ Encoders
  - ▶ Take the raw data from the CRTC and convert it to a particular format

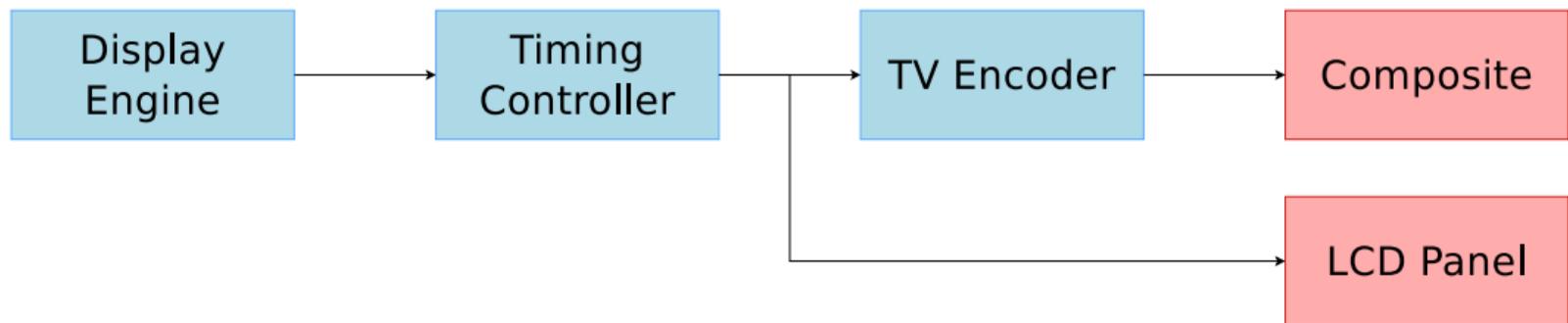


# KMS components

- ▶ Planes
  - ▶ Image source
  - ▶ Associated with one (or more!) framebuffer
  - ▶ Holds a resized / cropped version of that framebuffer
- ▶ CRTC
  - ▶ Take the planes, and does the composition
  - ▶ Contains the display mode and parameters
- ▶ Encoders
  - ▶ Take the raw data from the CRTC and convert it to a particular format
- ▶ Connectors
  - ▶ Outputs the encoded data to an external display
  - ▶ Handles hotplug events
  - ▶ Reads EDIDs

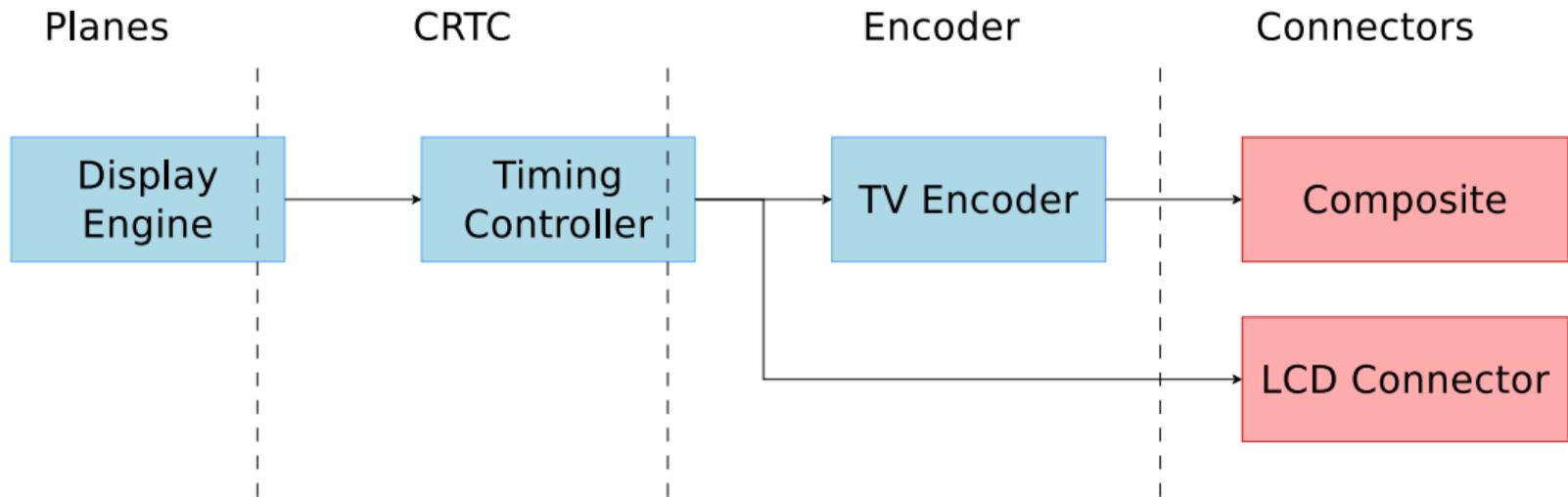


# Allwinner display pipeline



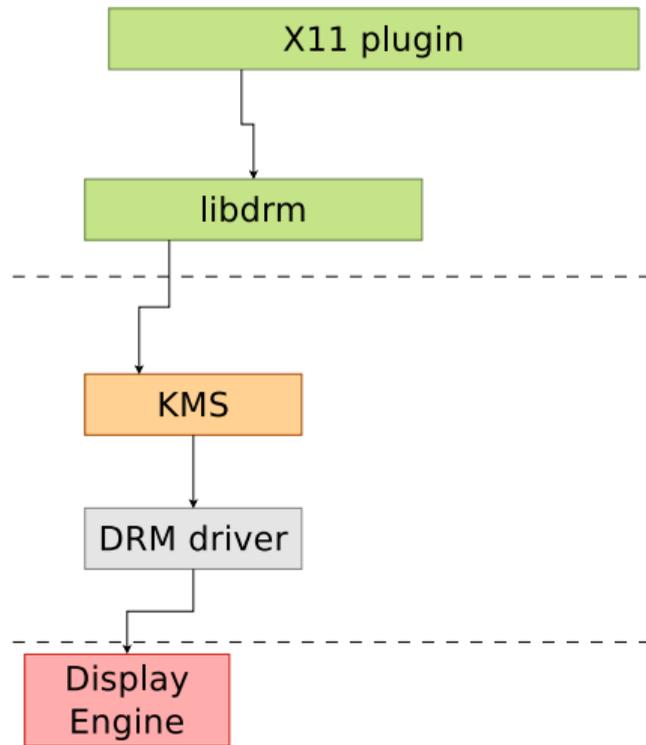


# DRM vs SoC pipeline



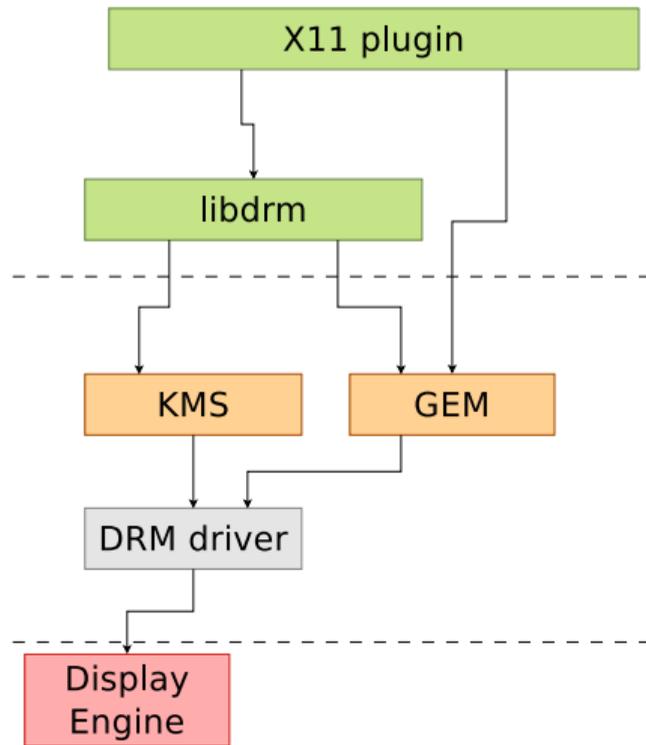


# DRM Stack: KMS



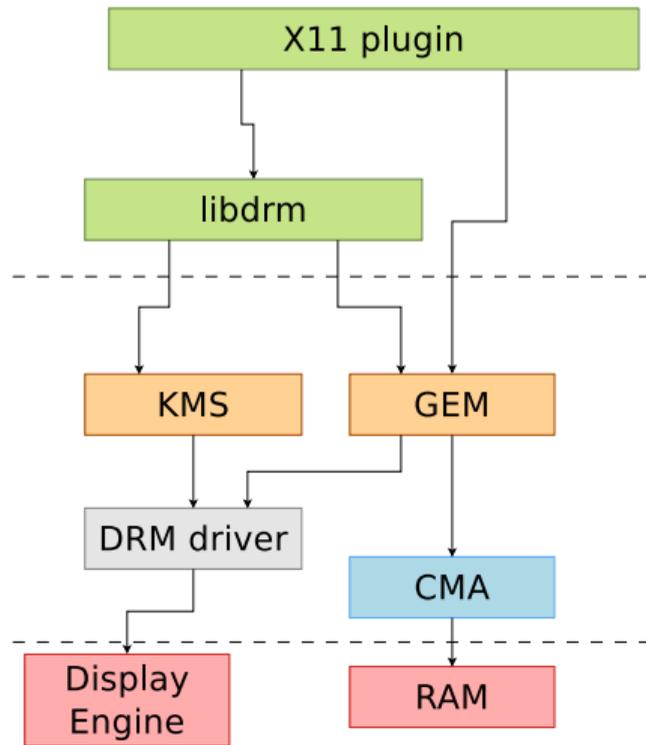


# DRM Stack: GEM



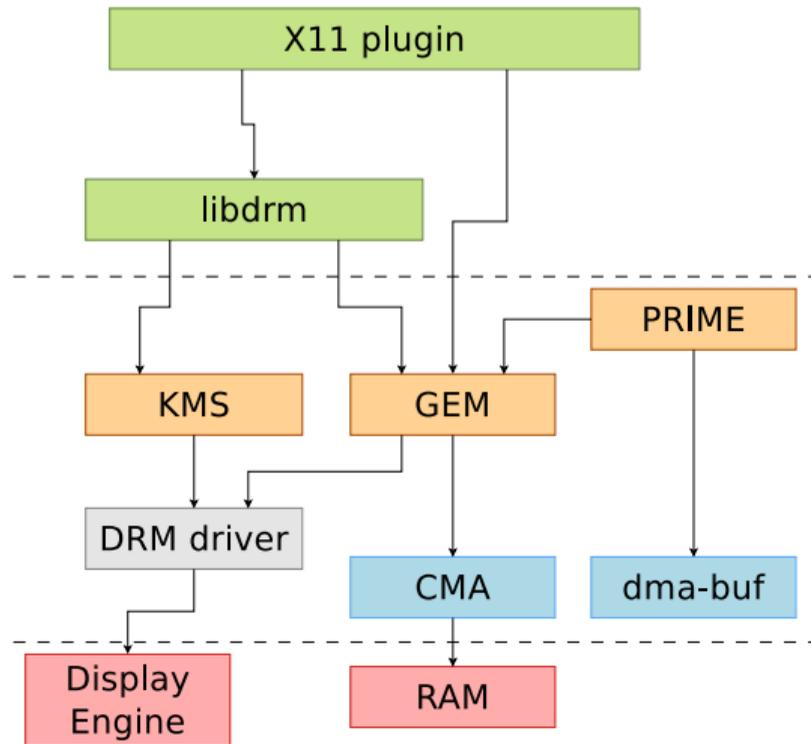


# DRM Stack: CMA



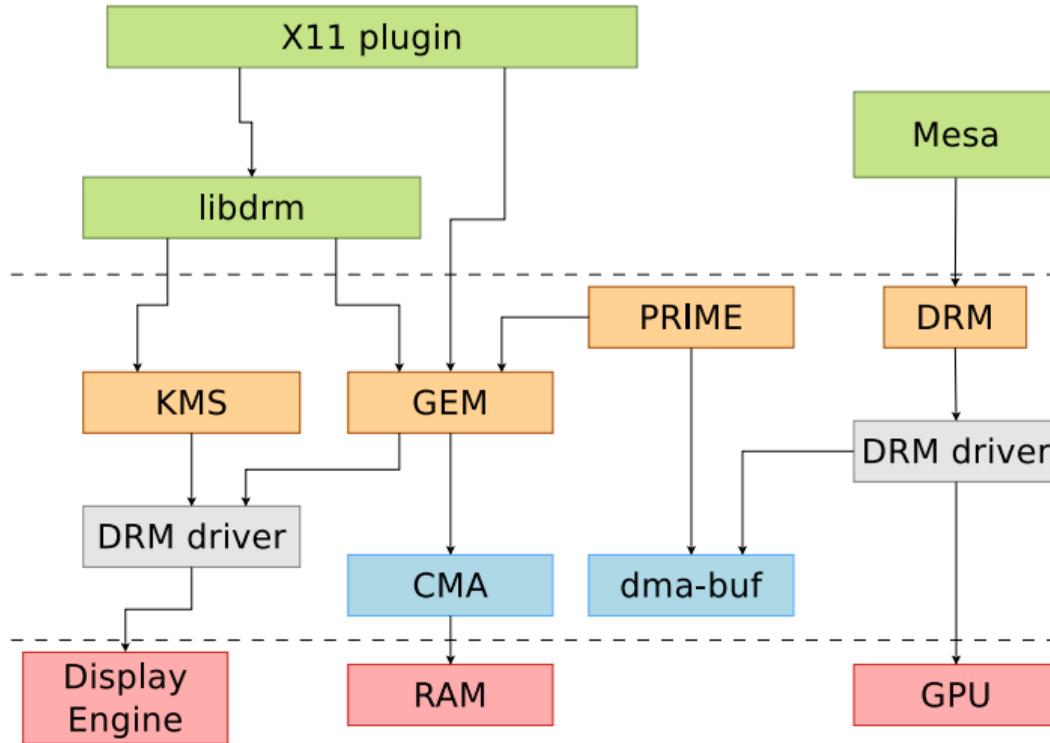


# DRM Stack: PRIME





# DRM Stack: GPUs





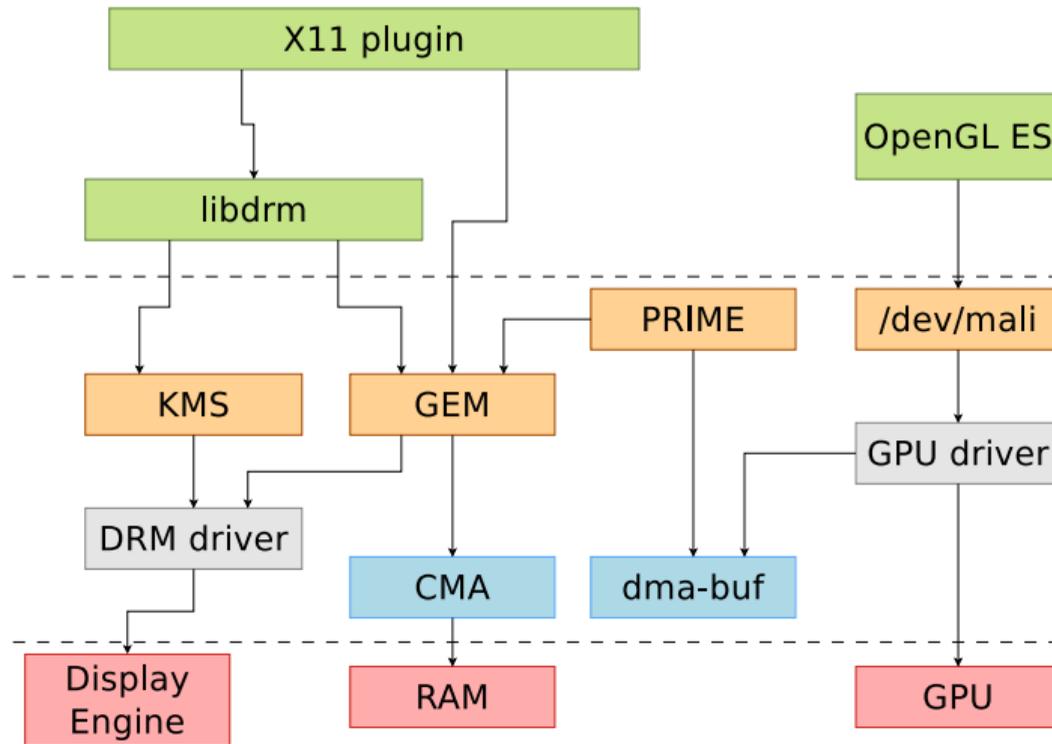
Vendor solutions...



- ▶ The GPU found in most Allwinner SoCs is the Mali-400 from ARM (with a variable number of cores)
- ▶ There are two options to support that GPU:
  - ▶ Lima
    - ▶ Reversed engineered proof-of-concept
    - ▶ Triggered the reverse engineering effort of the GPUs (freedreno, etnaviv, etc.)
    - ▶ Development (close to?) stopped three years ago, and then resumed a couple of monthes ago
  - ▶ ARM-Provided support
    - ▶ Featureful
    - ▶ Two parts: GPL kernel driver and proprietary OpenGL ES implementation



# DRM Stack: GPU





- ▶ Everything is provided by ARM on their website (if you're lucky)
- ▶ On the userspace side, you just need to put the library they provided on your system
- ▶ On the driver side, you need to create a platform glue that will deal with:
  - ▶ Memory mapping
  - ▶ Interrupts
  - ▶ Clocks
  - ▶ Reset lines
  - ▶ Power Domains
  - ▶ Basically everything needed for the GPU to operate properly on your SoC



## X11 integration

- ▶ We need a DDX (Device Dependent X) driver
- ▶ `xf86-video-modesetting` is working on top of KMS and GBM (MESA-defined user-space API to allocate buffers)
- ▶ ARM developed `xf86-video-armsoc` for SoC using a 3rd party GPU (Mali, PowerVR, Vivante, etc.)
- ▶ Relies on KMS for the display configuration, driver-specific ioctl for buffer allocations and vendor-provided OpenGL ES implementation
- ▶ Just have to write a small glue to use your driver allocator, and give some hints to X about what your hardware support (hw cursor, vblank, etc.)

# Questions? Suggestions? Comments?

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<http://bootlin.com/pub/conferences/2017/kr/ripard-drm>