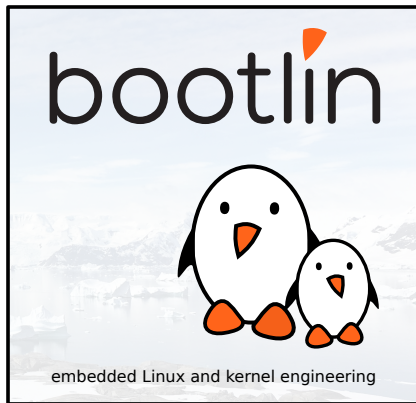




## Supporting the Camera Interface on the C.H.I.P

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Corrections, suggestions, contributions and translations are welcome!





- ▶ Embedded Linux engineer and trainer at Bootlin
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  - ▶ **Co-maintainer for the sunXi SoCs** from Allwinner
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- ▶ Living in **Toulouse**, south west of France



## Introduction



# C.H.I.P. ?

- ▶ 9\$ SBC
- ▶ Based on an Allwinner R8 (equivalent to A13)
- ▶ 1GHz Cortex-A8 CPU
- ▶ Mali 400 GPU
- ▶ Plenty of GPIOs to bitbang stuff (and real controllers too!)
- ▶ Running mainline-ish Linux kernel (4.4 at the moment)



# Development effort

- ▶ A significant part of the work already done
- ▶ But key features for a desktop-like application were missing
  - ▶ NAND support
  - ▶ Display, GPU
  - ▶ Audio, Camera, VPU
- ▶ Plus board specific developments
  - ▶ WiFi regulators
  - ▶ DIP



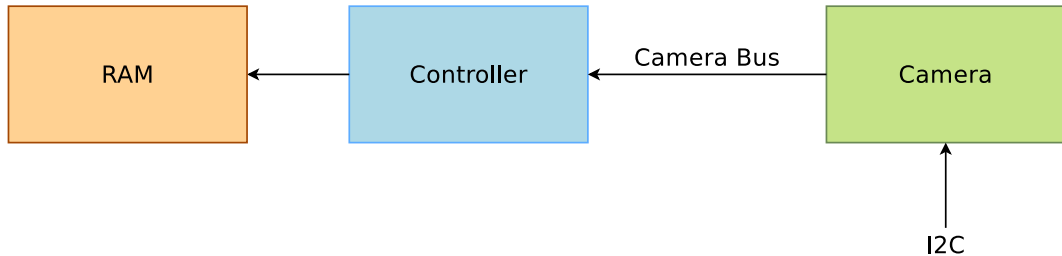
## Video Capture in Linux



- ▶ Introduced in 2002, in 2.5.46
- ▶ Supports a wide range of devices
  - ▶ Video Capture (Camera, tuners)
  - ▶ Memory to memory devices (Hardware codecs, scalers, deinterlacers)
  - ▶ Radio receivers and transceivers
  - ▶ SDR



## V4L2: A dumb pipeline







- ▶ There's a wide range of video formats...
- ▶ ... And even weird variations of them
- ▶ Most of the time, the controller and the sensor don't support the same set of formats
- ▶ Some negotiation needs to happen between the controller and the camera to agree on a common format.

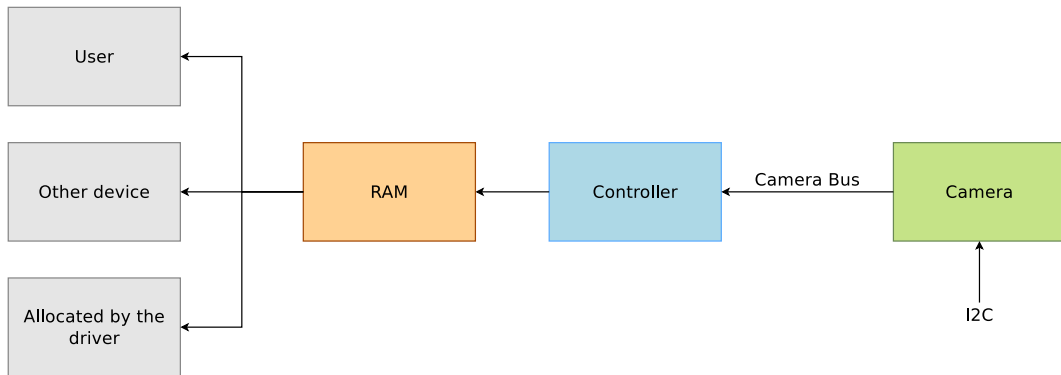


# Streaming

- ▶ You also need to implement the streaming hooks
- ▶ Addresses two things:
  - ▶ Memory Management: Buffer allocation, queuing and dequeuing
  - ▶ Streaming control
- ▶ With the formats, the only really needed operations



# Streaming modes





- ▶ Generic implementation of that streaming API
- ▶ Relies on a smaller, simpler set of callbacks to implement
- ▶ Different videobuf implementations, depending on your setup (backed by vmalloc, scatter gather DMA or contiguous DMA)
- ▶ Also has a notion of streaming modes, which control the source of the buffers, among
  - ▶ The driver
  - ▶ The user-space (if the device supports it)
  - ▶ Some other device (through DMA-BUF)
- ▶ The new callbacks are only there to tell videobuf the size and number of buffers to allocate, insert new buffers in a DMA chain, or start and stop the streaming



# Controls

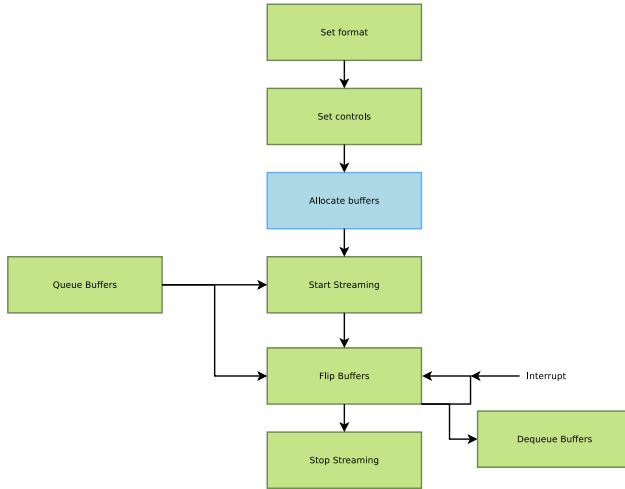
- ▶ Your device might need additional set up for things like
  - ▶ White balance
  - ▶ Saturation
  - ▶ Brightness
  - ▶ etc.
- ▶ By default, no controls are implemented, but the driver needs to declare them during probe, and handle them in a dedicated callback.



- ▶ You'll usually have two drivers:
  - ▶ One for the controller, usually in `drivers/media/platform`
  - ▶ And one for the camera, in `drivers/media/i2c`
- ▶ By default, exposed to the userspace as one single device `/dev/videoX`
- ▶ You need some synchronization between the two: `v4l2-async`
- ▶ Very similar to what is found in ASoC or DRM
- ▶ Basically a two-stage probe



# State machine





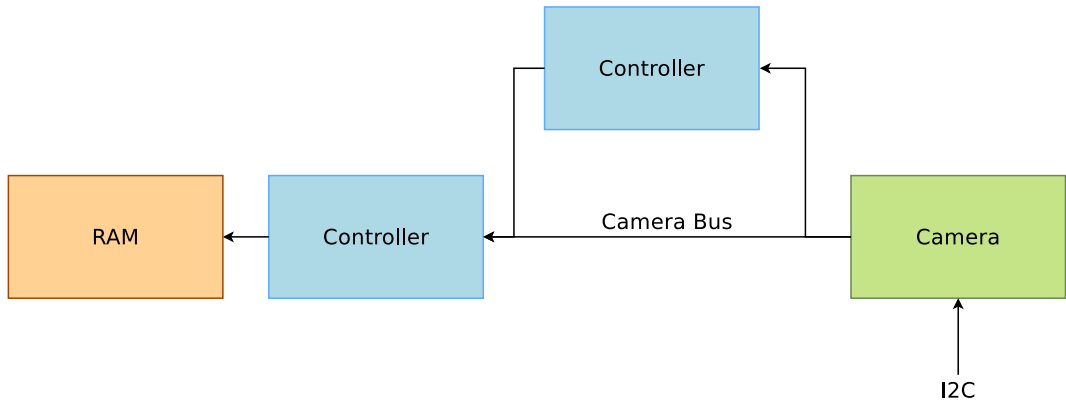
# Multi-plane

- ▶ Some formats require multi-plane support
- ▶ Depending on the format, it might need 1 to 3 buffers
- ▶ Supported in v4l through a different capture type
- ▶ The callbacks are different too, but very similar
- ▶ You basically just have to deal with more buffers





## More complicated setup





- ▶ When the pipeline gets more complicated, the amount of controls to expose in the video device starts to be impossible to deal with
- ▶ The media controller API allows to expose one device file per component in the pipeline
- ▶ Each of them can be accessed independently, for example with media-ctl
- ▶ It might even simplify your driver, because all the format negotiation will not be relevant anymore.



# Tests!

- ▶ v4l2-compliance is awesome
- ▶ v4l2-info
- ▶ yavta
- ▶ Any v4l enabled application (Cheese?)



## Future developments

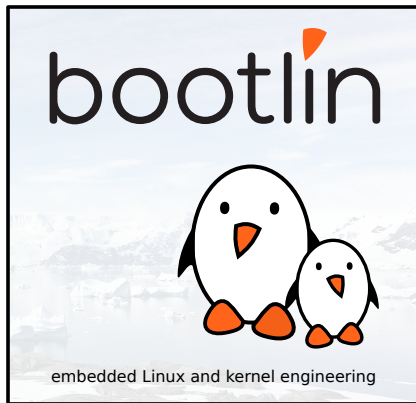
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# Integration with DRM

- ▶ Our camera and display engines can work in the same format (but no driver support for it yet in the DRM driver)
- ▶ The display engine is even able to re-scale the video coming from the camera (but there's no driver support for it yet).
- ▶ Finding which component in userspace could do that. Gstreamer? Something a la ALSA cards configuration files?



# VPU Support

- ▶ We have some work on-going to support the VPU on the Allwinner SoCs
- ▶ Reverse engineering
- ▶ Decoding works for some codecs and image formats
- ▶ Encoding is not really understood right now
- ▶ Figure it out and support encoding through the VPU

# Questions? Suggestions? Comments?

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<http://bootlin.com/pub/conferences/2016/elce/ripard-v41>