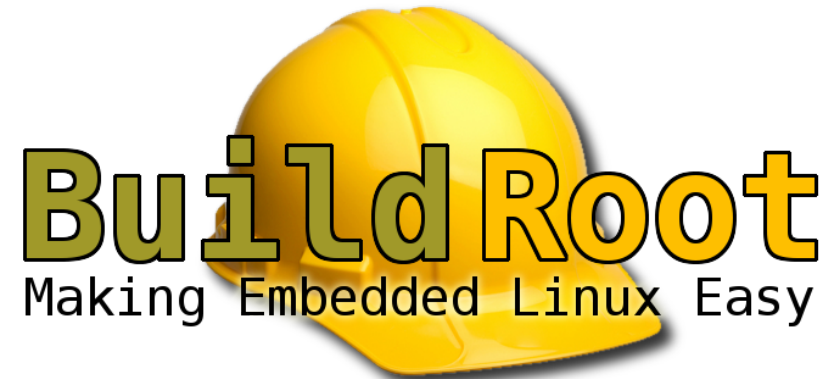
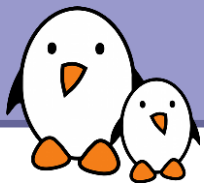


Building embedded Linux systems with Buildroot

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Bootlin
<https://bootlin.com/>





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Document sources, updates and translations:
<https://bootlin.com/doc/training/buildroot/>

Corrections, suggestions, contributions and
translations are welcome!

Latest update: Jul 25, 2018





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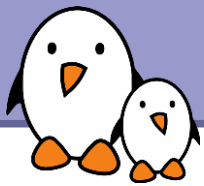
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Leveraging free software

Thousands of free software packages are available and can be leveraged to build embedded systems

With free software

- You have control over the source

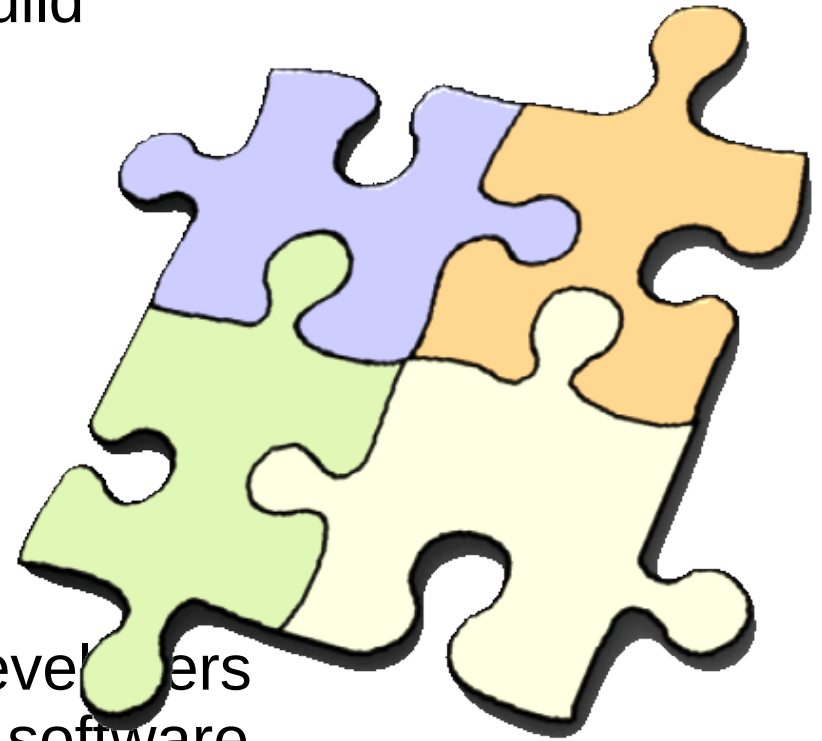
- Bugs can be fixed

- New features can be added

- Your system can be customized

In theory, the system designers and developers have a lot of flexibility thanks to free software

However, leveraging the existing free software packages may not be very easy.





Using a distribution

Distributions provide ready-to-use binary packages

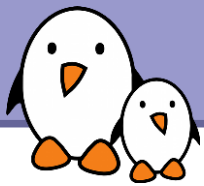
Some distributions, such as Debian, are available for embedded architectures (ARM, MIPS, PowerPC)

They make it relatively easy to get a working system, but

- The maintainer of each package has made configuration choices that don't necessarily match your choices (soft float vs. hard float, EABI vs OABI, feature A or not feature A)

- You don't have a lot of control on system integration (initialization scripts, dependencies of the components)

- If you want to integrate fixes or new features, you need to rebuild the packages. While this may not be very difficult, there's usually no automated infrastructure to rebuild the whole system.



Manually

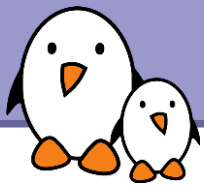
You can configure, compile, install and integrate all the free software components needed to build a working Linux system manually.

It gives you full flexibility, but

- You need to know the dependencies between all the components

- Cross-compiling is usually a tedious process, sometimes requiring package source code changes

- You don't have an automated procedure to rebuild your system, which might be needed if you want to integrate a bug fix or a new feature



Build systems

Build systems allow an embedded Linux developer to generate a working embedded Linux system from scratch.

They automate the process of downloading, configuring, compiling and installing all the free software packages

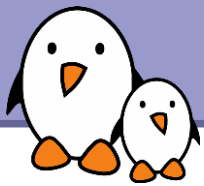
- You have a well-known procedure for rebuilding your system from scratch

- You can easily integrate patches, bug fixes or new upstream versions

- Your colleagues can easily take over your work, as there's a documented procedure for system generation

The build system already knows about most free software packages

- Dependencies are managed, and cross-compiling issues are already solved.



Entering Buildroot

Buildroot <<http://www.buildroot.net>> is a set of Makefiles that automates the process of building a cross-compiling toolchain and a root filesystem for an embedded system.

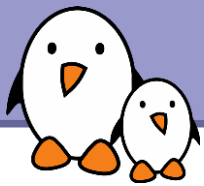
Buildroot has been initially developed by uClibc developers.

For a long time, it had no maintainer and no releases were delivered

Since January 2009, Buildroot now has an official maintainer, Peter Korsgaard

In February 2009, the first stable release has been published, Buildroot 2009.02. A new release will be published every 3 months.

An opportunity to take a fresh look at Buildroot !



Buildroot users

They are already using Buildroot

ATMEL for their AVR32 development kit

<http://www.atmel.no/buildroot/buildroot-doc.html>

Gumstix

<http://docwiki.gumstix.org/index.php/Buildroot>

Armadeus (ARM boards with FPGA)

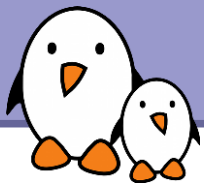
<http://www.armadeus.com>

Calao Systems

<http://www.calao-systems.com/>

And probably a lot more !





Buildroot configuration

Buildroot uses the Kconfig configuration system

Offers a menuconfig-like interface

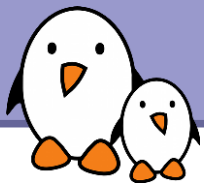
Saves the configuration in a .config file

```
.config - buildroot v2009.05-svn Configuration

Buildroot Configuration
Arrow keys navigate the menu. <Enter> selects submenus --->.
Highlighted letters are hotkeys. Pressing <Y> selects a feature, while
<N> will exclude a feature. Press <Esc><Esc> to exit, <?> for Help, </>
for Search. Legend: [*] feature is selected [ ] feature is excluded

[*] Target Architecture (arm) --->
    Target Architecture Variant (generic_arm) --->
    Target ABI (EABI) --->
    Target options --->
    Build options --->
    Toolchain --->
    Package Selection for the target --->
    Target filesystem options --->
    Kernel --->
    ---
    Load an Alternate Configuration File
    Save an Alternate Configuration File

<Select> < Exit > < Help >
```



Main configuration

Target architecture

arm, armeb, avr32, cris, i386, mips, mipsel, powerpc, superh, superh64, x86_64

Architecture variant

For ARM, for example: Generic, ARM7TDMI, ARM610, ARM710, ARM720T, ARM920T, Xscale, etc.

ABI selection

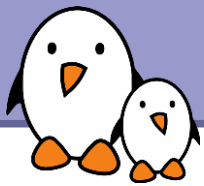
For ARM, EABI or OABI

Target options

Build options

Host tools to use, directory definition

Install documentation? Debugging symbols? Strip? Level of gcc optimization?



Toolchain configuration

Buildroot can either build a toolchain (limited to uClibc toolchains) or re-use an existing external toolchain (limited to sysroot-able toolchains)

In the case of a toolchain built by Buildroot, the configuration allows to select things such as

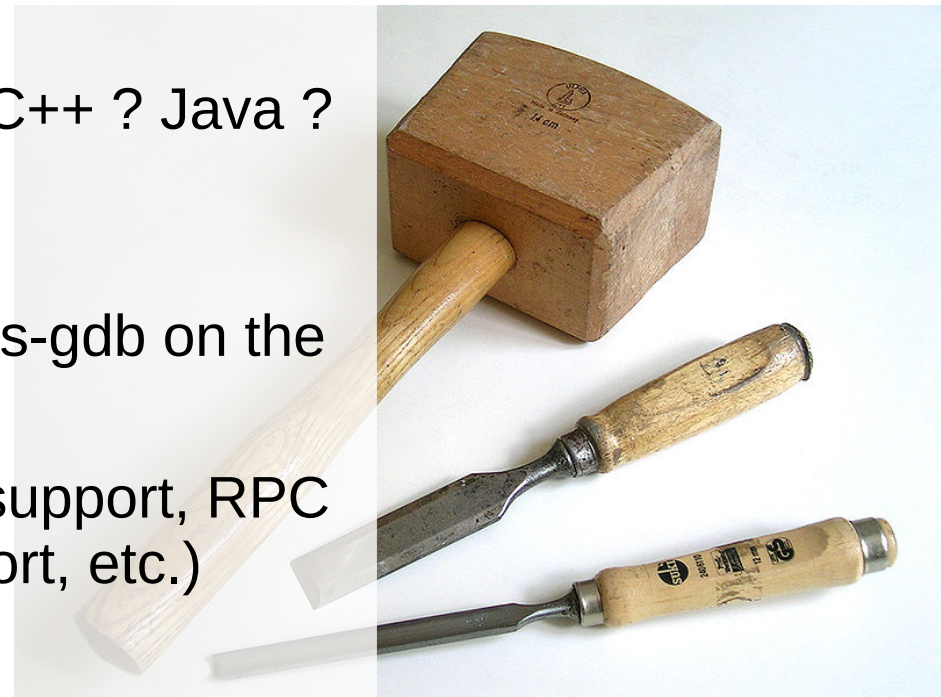
- Kernel headers version

- uClibc version and configuration

- GCC version and options (Fortran ? C++ ? Java ? Objective C?)

- GDB version and options
(gdbserver, gdb on the target, cross-gdb on the host)

- General toolchain options (large file support, RPC support, IPv6 support, locale support, etc.)





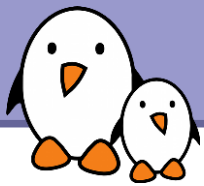
Package selection (1/3)

Several hundreds of packages can be selected, with of course a focus on packages useful for embedded devices

Dependencies between packages are handled, either through depends on relation or select relation.

Main packages: busybox, bash, bzip2, diffutils, flex, native toolchain, grep, bootutils, cups, at, beecrypt, dash, file, gamin, less, lsof, ltrace, memstat, module-init-tools, procps, psmisc, screen, strace, sudo, syslogd, klogd, util-linux, which, etc.

Core libraries: libconfig, libconfuse, libdaemon, libelf, libevent, libgcrypt, libiconv, libidn, liblockfile, liboil, libsysfs, etc.



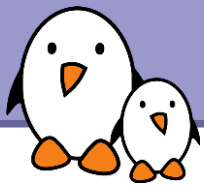
Package selection (2/3)

Databases: MySQL client, sqlite

Text editors: ed, nano, uemacs, vim

Networking: argus, avahi, axel, boa, bind, bridge-utils, DHCP support, dnsmasq, dropbear, ethtool, haserl, ifplugd, iperf, iproute2, ipsec-tools, iptables, kismet, l2tp, lighttpd, linkns, lrzsz, mDNSresponder, mii-diag, mrouted, nbd, ncftp, netcat, netkitbase, netkitteln, netplug, netsnmp, nfs-utils, ntp, openntpd, openssh, openssl, openvpn, portmap, pppd, pppoe, pptp-linux, proftpd, quagga, isisd, samba, rsync, stunnel, tcpdump, tftpd, thttpd, vsftpd, wireless tools, etc.

Hardware/system tools: dm, dmraid, e2fsprogs, fis, libfuse, hal, hdparm, hotplug, i2c-tools, input-tools, iostat, libaio, libraw1394, libusb, lm-sensors, lvm2, mdadm, mtd utils, pciutils, setserial, udev, usbutils, etc.



Package selection (3/3)

Audio/video: aumix, flac, gstreamer with plugins, libmad, libmpd, libogg, libtheora, libvorbis, madplay, mpg123, mplayer, speex, vlc, festival

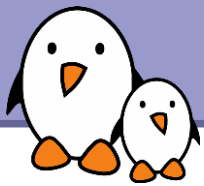
Graphic libraries: ncurses, slang, dialog, DirectFB, imagemagick, jpeg, libpng, libungif, pixman, SDL, QT Embedded, Gtk (atk, cairo, pango, glib), fontconfig, Freetype, Matchbox, X.org Kdrive and a few X applications (window managers, etc.)

Compressor/decompressors

Package managers: ipkg, portage, rpm

Interpreters, languages: lua, microp Perl, python, ruby, tcl, php

Misc: XML libraries, Java, Games



Filesystem and kernel configuration

Output format selection for the root filesystem

cramfs, cloop, ext2, jffs2, ubifs, squashfs, tar, cpio, initramfs, romfs.

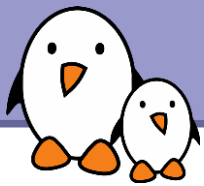
Of course, the raw root filesystem is also available

Bootloader configuration

U-Boot supported

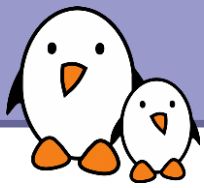
Kernel configuration

The version, configuration, additional patches and the kernel binary format (ulmage, zImage, bzImage) can be specified



Demo time !

Building a system with Busybox, DirectFB and
example applications



Directory hierarchy

In the sources

`docs/`, documentation

`package/`, the configuration items and Makefiles for building the userspace packages

`project/`, the configuration items and Makefiles for the project concept (several projects in the same Buildroot tree)

`scripts/` various utilities

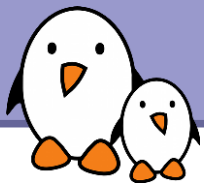
`target/linux/`, building the Linux kernel

`target/<fstype>/`, generating the root filesystem image

`target/device/`, ready-made configuration for supported boards

`target/generic/target_skeleton/`, the default root filesystem skeleton

`toolchain/`, building a cross-compiling toolchain



Using Buildroot in a nutshell

Download the latest stable version, or get a development version from the SVN (better to report issues)

```
make menuconfig
```

```
make
```

Get your raw root filesystem in

```
project_build_ARCH/PROJECT/root/
```

Get your root filesystem image and kernel image in

```
binaries/PROJECT/
```

Location of output directories can be changed using

```
O=/path/to
```



Generated directories

`build_ARCH`

One directory for each package, where it has been configured and built

`staging_dir`, where the toolchain and packages are installed, and where non-stripped versions of the binaries/libraries can be found

`project_build_ARCH/PROJECT`

`autotools_stamps`, stamps for handling dependencies between build steps

`buildroot-config`, header files related to Buildroot configuration mechanism

`root`, the root filesystem for the target

`toolchain_build_ARCH`

Where the toolchain components are configured and built



Buildroot: adding new packages

Create a new directory, for example `package/gqview/`

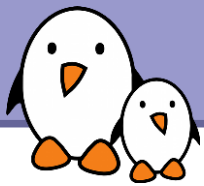
Add a `Config.in` file in this directory to describe the configuration options

```
config BR2_PACKAGE_GQVIEW
    bool "gqview"
    select BR2_PACKAGE_PKGCONFIG
    help
        GQview is an image viewer for Unix
        operating systems

        http://prdownloads.sourceforge.net/gqview
```

Insert the new `Config.in` file in the configuration system by adding to `package/Config.in`

```
source "package/gqview/Config.in"
```

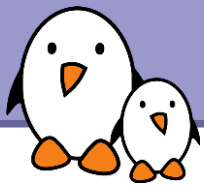


Buildroot: adding new packages (2)

Create the `gqview.mk` file to describe the build steps. The following example uses the `Makefile.autotools.in` machinery, which makes it easy to support autotools based packages

```
GQVIEW_VERSION = 2.1.5
GQVIEW_SOURCE = gqview-$(GQVIEW_VERSION).tar.gz
GQVIEW_SITE = http://prdownloads.sourceforge.net/gqview
GQVIEW_AUTORECONF = NO
GQVIEW_INSTALL_STAGING = NO
GQVIEW_INSTALL_TARGET = YES
GQVIEW_DEPENDENCIES = uclibc pkgconfig libgtk2
$(eval $(call AUTOTARGETS,package,gqview))
```

Patches can also be added in the package directory, with filenames like `pkgname-version-feature.patch`. They will be automatically applied before configuring the package.



Buildroot: adding new packages (3)

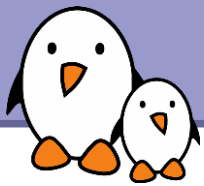
Packages not based on autotools, or needing specific configuration, compilation and installation steps can be handled manually.

```
GZIP_VERSION:=1.3.12
GZIP_SOURCE:=gzip-$(GZIP_VERSION).tar.gz
GZIP_SITE:=$(BR2_GNU_MIRROR)/gzip
GZIP_DIR:=$(BUILD_DIR)/gzip-$(GZIP_VERSION)
GZIP_CAT:=$(ZCAT)
GZIP_BINARY:=$(GZIP_DIR)/gzip
GZIP_TARGET_BINARY:=$(TARGET_DIR)/bin/zmore

$(DL_DIR)/$(GZIP_SOURCE):
    $(call DOWNLOAD,$(GZIP_SITE),$(GZIP_SOURCE))

gzip-source: $(DL_DIR)/$(GZIP_SOURCE)

$(GZIP_DIR)/.unpacked: $(DL_DIR)/$(GZIP_SOURCE)
    $(GZIP_CAT) $(DL_DIR)/$(GZIP_SOURCE) | \
    tar -C $(BUILD_DIR) $(TAR_OPTIONS) -
    touch $(GZIP_DIR)/.unpacked
```



Buildroot: adding new packages (4)

```
$(GZIP_DIR)/.configured: $(GZIP_DIR)/.unpacked
    (cd $(GZIP_DIR); rm -rf config.cache; \
        $(TARGET_CONFIGURE_OPTS) \
        $(TARGET_CONFIGURE_ARGS) \
        ./configure \
        --target=$(GNU_TARGET_NAME) \
        --host=$(GNU_TARGET_NAME) \
        --build=$(GNU_HOST_NAME) \
        --prefix=/usr \
        --exec-prefix=/ \
        $(DISABLE_NLS) \
        $(DISABLE_LARGEFILE) \
    )
    touch $(GZIP_DIR)/.configured

$(GZIP_BINARY): $(GZIP_DIR)/.configured
    $(MAKE) CC=$(TARGET_CC) -C $(GZIP_DIR)
```

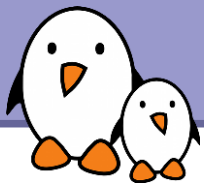


Buildroot : adding new packages (5)

```
$(GZIP_TARGET_BINARY): $(GZIP_BINARY)
    $(MAKE) DESTDIR=$(TARGET_DIR) CC=$(TARGET_CC) \
        -C $(GZIP_DIR) install-strip
ifndef $(BR2_HAVE_INFOPAGES),y
    rm -rf $(TARGET_DIR)/usr/share/info
endif
ifndef $(BR2_HAVE_MANPAGES),y
    rm -rf $(TARGET_DIR)/usr/share/man
endif

gzip: uclibc $(GZIP_TARGET_BINARY)
gzip-clean:
    $(MAKE) DESTDIR=$(TARGET_DIR) CC=$(TARGET_CC) \
        -C $(GZIP_DIR) uninstall
    -$(MAKE) -C $(GZIP_DIR) clean
gzip-dirclean:
    rm -rf $(GZIP_DIR)

ifeq $(BR2_PACKAGE_GZIP),y
TARGETS+=gzip
endif
```

Future work

Cleanup

The project has been unmaintained for some time, so some cleanup is needed

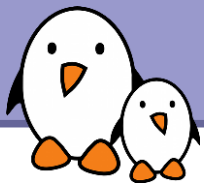
More packages

Of course !

Better support for external toolchains

Including glibc toolchains

\$YOURIDEA



Feedback and community

Buildroot is organized like a typical free software community, it is not trusted by any company, even though some of the developers are obviously professionals

Mailing-list, at <http://lists.busybox.net/mailman/listinfo/buildroot>

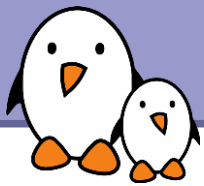
Very helpful support !

Bug tracker at <https://bugs.uclibc.org/>

Subversion repository at <svn://uclibc.org/trunk/buildroot>

Documentation at <http://www.buildroot.net/buildroot.html>

Feel free to test, report and contribute !



Alternatives

Very similar to Buildroot

PTXdist, developed by Pengutronix

http://www.pengutronix.de/software/ptxdist/index_en.html

LTIB, developed mainly by Freescale.

Good support for Freescale boards

<http://www.bitshrine.org/>

Slightly different approaches

OpenEmbedded, more flexible but also far more complicated

<http://www.openembedded.org>

Gentoo Embedded

<http://www.gentoo.org/proj/en/base/embedded/handbook/>

Let's discuss these, other alternatives, their advantages, drawbacks, and future work in a BOF session on Wednesday at 1 PM



Questions?



BuildRoot

Making Embedded Linux Easy

<http://www.buildroot.net>