These slides are the training materials for Bootlin’s *Yocto Project and OpenEmbedded system development* training course.

If you are interested in following this course with an experienced Bootlin trainer, we offer:

- **Public online sessions**, opened to individual registration. Dates announced on our site, registration directly online.
- **Dedicated online sessions**, organized for a team of engineers from the same company at a date/time chosen by our customer.
- **Dedicated on-site sessions**, organized for a team of engineers from the same company, we send a Bootlin trainer on-site to deliver the training.

Details and registrations:  
[https://bootlin.com/training/yocto](https://bootlin.com/training/yocto)

Contact: training@bootlin.com
Bootlin introduction

▶ Engineering company
  • In business since 2004
  • Before 2018: *Free Electrons*

▶ Team based in France and Italy

▶ Serving *customers worldwide*

▶ **Highly focused and recognized expertise**
  • Embedded Linux
  • Linux kernel
  • Embedded Linux build systems

▶ **Strong open-source** contributor

▶ Activities
  • **Engineering** services
  • **Training** courses

▶ [https://bootlin.com](https://bootlin.com)
Bootlin engineering services

Bootloader / firmware development
U-Boot, Barebox, OP-TEE, TF-A, ...

Linux kernel porting and driver development

Linux BSP development, maintenance and upgrade

Embedded Linux build systems
Yocto, OpenEmbedded, Buildroot, ...

Embedded Linux integration
Boot time, real-time, security, multimedia, networking

Open-source upstreaming
Get code integrated in upstream Linux, U-Boot, Yocto, Buildroot, ...
Bootlin training courses

- Embedded Linux system development
  - On-site: 4 or 5 days
  - Online: 7 * 4 hours

- Linux kernel driver development
  - On-site: 5 days
  - Online: 7 * 4 hours

- Yocto Project system development
  - On-site: 3 days
  - Online: 4 * 4 hours

- Buildroot system development
  - On-site: 3 days
  - Online: 5 * 4 hours

- Understanding the Linux graphics stack
  - On-site: 2 days
  - Online: 4 * 4 hours

- Embedded Linux boot time optimization
  - On-site: 3 days
  - Online: 4 * 4 hours

- Real-Time Linux with PREEMPT_RT
  - On-site: 2 days
  - Online: 3 * 4 hours

- Linux debugging, tracing, profiling and performance analysis
  - On-site: 3 days
  - Online: 4 * 4 hours
Bootlin, an open-source contributor

- Strong contributor to the **Linux** kernel
  - In the top 30 of companies contributing to Linux worldwide
  - Contributions in most areas related to hardware support
  - Several engineers maintainers of subsystems/platforms
  - 8000 patches contributed
  - [https://bootlin.com/community/contributions/kernel-contributions/](https://bootlin.com/community/contributions/kernel-contributions/)

- Contributor to **Yocto Project**
  - Maintainer of the official documentation
  - Core participant to the QA effort

- Contributor to **Buildroot**
  - Co-maintainer
  - 5000 patches contributed

- Significant contributions to U-Boot, OP-TEE, Barebox, etc.

- Fully **open-source training materials**
Bootlin on-line resources

▶ Website with a technical blog:
   https://bootlin.com

▶ Engineering services:
   https://bootlin.com/engineering

▶ Training services:
   https://bootlin.com/training

▶ Twitter:
   https://twitter.com/bootlincom

▶ LinkedIn:
   https://www.linkedin.com/company/bootlin

▶ Elixir - browse Linux kernel sources on-line:
   https://elixir.bootlin.com

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Generic course information

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Corrections, suggestions, contributions and translations are welcome!
Two supported hardware platforms

Two variants for this course, each using a different hardware platform.

Beaglebone Black
https://bootlin.com/doc/training/yocto/

STM32MP157D-DK1 Discovery
https://bootlin.com/doc/training/yocto-stm32/
Shopping list: BeagleBone Black Wireless variant

- Beaglebone Black or Beaglebone Black Wireless, USB-A to micro B power cable included
  https://www.mouser.fr/ProductDetail/BeagleBoard-by-GHI/BBBWL-SC-562?qs=k%2Fsw%252B3Yi%2FUbELBjXqpiBUQ%3D%3D

- USB Serial Cable - 3.3 V - female ends (for serial console)
  https://www.olimex.com/Products/Components/Cables/USB-Serial-Cable/USB- SERIAL-F/

- Nintendo Nunchuk with UEXT connector
  https://www.olimex.com/Products/Modules/Sensors/MOD-WII/MOD-Wii-UEXT- NUNCHUCK/

- Breadboard jumper wires - Male ends (to connect to Nunchuk)
  https://www.olimex.com/Products/Breadboarding/JUMPER-WIRES/JW-110x10/

- Micro SD card with 8 GB capacity
Shopping list: STM32MP1 Discovery Kit variant

- STMicroelectronics STM32MP157D-DK1 Discovery kit

- USB-C cable for the power supply

- USB-A to micro B cable for the serial console

- RJ45 cable for networking

- Nintendo Nunchuk with UEXT connector
  https://www.olimex.com/Products/Modules/Sensors/MOD-WII/MOD-Wii-UEXT-NUNCHUCK/

- Breadboard jumper wires - Male ends
  https://www.olimex.com/Products/Breadboarding/JUMPER-WIRES/JW-110x10/

- Micro SD card with 8 GB capacity
Supported hardware

BeagleBone Black or BeagleBone Black Wireless, from BeagleBoard.org

- Texas Instruments AM335x (ARM Cortex-A8 CPU)
- SoC with 3D acceleration, additional processors (PRUs) and lots of peripherals.
- 512 MB of RAM
- 4 GB of on-board eMMC storage
- USB host and USB device, microSD, micro HDMI
- WiFi and Bluetooth (wireless version), otherwise Ethernet
- 2 x 46 pins headers, with access to many expansion buses (I2C, SPI, UART and more)
- A huge number of expansion boards, called capes. See https://elinux.org/Beagleboard:BeagleBone_Capes.
Supported hardware

Discovery Kits from STMicroelectronics: STM32MP157A-DK1, STM32MP157D-DK1, STM32MP157C-DK2 or STM32MP157F-DK2

- STM32MP157 (Dual Cortex-A7 + Cortex-M4) CPU from STMicroelectronics
- 512 MB DDR3L RAM
- Gigabit Ethernet port
- 4 USB 2.0 host ports, 1 USB-C OTG port
- 1 Micro SD slot
- On-board ST-LINK/V2-1 debugger
- Misc: buttons, LEDs, audio codec
- LCD touchscreen (DK2 only)
- Currently sold at 72 EUR + VAT (DK1) and 113 EUR + VAT (DK2) at Mouser

Board and CPU documentation, design files, software: A-DK1, D-DK1, C-DK2, F-DK2
Training quiz and certificate

- You have been given a quiz to test your knowledge on the topics covered by the course. That’s not too late to take it if you haven’t done it yet!
- At the end of the course, we will submit this quiz to you again. That time, you will see the correct answers.
- It allows Bootlin to assess your progress thanks to the course. That’s also a kind of challenge, to look for clues throughout the lectures and labs / demos, as all the answers are in the course!
- Another reason is that we only give training certificates to people who achieve at least a 50% score in the final quiz and who attended all the sessions.
Participate!

During the lectures...

- Don’t hesitate to ask questions. Other people in the audience may have similar questions too.
- Don’t hesitate to share your experience too, for example to compare Linux with other operating systems you know.
- Your point of view is most valuable, because it can be similar to your colleagues’ and different from the trainer’s.

- In on-line sessions
  - Please always keep your camera on!
  - Also make sure your name is properly filled.
  - You can also use the "Raise your hand" button when you wish to ask a question but don’t want to interrupt.

- All this helps the trainer to engage with participants, see when something needs clarifying and make the session more interactive, enjoyable and useful for everyone.
Collaborate!

As in the Free Software and Open Source community, collaboration between participants is valuable in this training session:

▶ Use the dedicated Matrix channel for this session to add questions.
▶ If your session offers practical labs, you can also report issues, share screenshots and command output there.
▶ Don’t hesitate to share your own answers and to help others especially when the trainer is unavailable.
▶ The Matrix channel is also a good place to ask questions outside of training hours, and after the course is over.
Prepare your lab environment

- Download and extract the lab archive
Simplified Linux system architecture

Userspace
- Application
- Application
- C library

Linux kernel
- Task/memory management
- Networking
- Device drivers
- Filesystems

Bootloader

Hardware
Overall Linux boot sequence

**Bootloader**
- Loads the DTB and kernel to RAM, starts the kernel

**Kernel**
- Initializes hardware devices and kernel subsystems
- Mounts the root filesystem indicated by root=
- Starts the init application, /sbin/init by default

**/sbin/init**
- Starts other user space services and applications

**Shell**

**Other applications**

**Root filesystem**
**Embedded Linux work**

- **BSP work**: porting the bootloader and Linux kernel, developing Linux device drivers.
- **System integration work**: assembling all the user space components needed for the system, configure them, develop the upgrade and recovery mechanisms, etc.
- **Application development**: write the company-specific applications and libraries.
Complexity of user space integration
## System integration: several possibilities

<table>
<thead>
<tr>
<th></th>
<th>Pros</th>
<th>Cons</th>
</tr>
</thead>
</table>
| **Building everything manually** | Full flexibility  
Learning experience | Dependency hell  
Need to understand a lot of details  
Version compatibility  
Lack of reproducibility |
| **Binary distribution**  
Debian, Ubuntu, Fedora, etc. | Easy to create and extend | Hard to customize  
Hard to optimize (boot time, size)  
Hard to rebuild the full system from source  
Large system  
Uses native compilation (slow)  
No well-defined mechanism to generate an image  
Lots of mandatory dependencies  
Not available for all architectures |
| **Build systems**  
Buildroot, Yocto, PTXdist, etc. | Nearly full flexibility  
Built from source: customization and optimization are easy  
Fully reproducible  
Uses cross-compilation  
Have embedded specific packages not necessarily in desktop distros  
Make more features optional | Not as easy as a binary distribution  
Build time |
Building from source → lot of flexibility
Cross-compilation → leveraging fast build machines
Recipes for building components → easy
A wide range of solutions: Yocto/OpenEmbedded, PTXdist, Buildroot, OpenWRT, and more.

Today, two solutions are emerging as the most popular ones

- **Yocto/OpenEmbedded**
  Builds a complete Linux distribution with binary packages. Powerful, but somewhat complex, and quite steep learning curve.

- **Buildroot**
  Builds a root filesystem image, no binary packages. Much simpler to use, understand and modify.
Yocto Project and Poky reference system overview
The Yocto Project overview
The Yocto Project is an open source collaboration project that allows to build custom embedded Linux-based systems.

It has been initiated by the Linux Foundation in 2010 and is still managed by one of its fellows: Richard Purdie.
Yocto: principle

- Yocto always builds binary packages (a "distribution")
- The final root filesystem is generated from the package feed
- The big picture is way more complex
In Yocto / OpenEmbedded, the *build engine* is implemented by the *bitbake* program

- **bitbake** is a task scheduler, like *make*
- **bitbake** parses text files to know what it has to build and how
- It is written in Python (need Python 3 on the development host)
Lexicon: recipes

- The main kind of text file parsed by bitbake is *recipes*, each describing a specific software component.
- Each *Recipe* describes how to fetch and build a software component: e.g. a program, a library or an image.
- They have a specific syntax.
- bitbake can be asked to build any recipe, building all its dependencies automatically beforehand.
The build process implemented by a recipe is split in several *tasks*. Each task performs a specific step in the build. Examples: fetch, configure, compile, package. Tasks have dependencies over other tasks (including on tasks of other recipes).
The input to `bitbake` is collectively called *metadata*. Metadata includes *configuration files, recipes, classes* and *include files*. Metadata is organized in *layers*, which can be composed together to get various components:

- A layer is a set of recipes, configurations files and classes matching a common purpose.
  - For Texas Instruments board support, the *meta-ti-bsp* layer is used.
- Multiple layers are used for a project, depending on the needs.

**`openembedded-core`** is the core layer:

- All other layers are built on top of `openembedded-core`.
- It supports the ARM, MIPS (32 and 64 bits), PowerPC, RISC-V and x86 (32 and 64 bits) architectures.
- It supports QEMU emulated machines for these architectures.
The word *Poky* has several meanings

- Poky is a git repository that is assembled from other git repositories: bitbake, openembedded-core, yocto-docs and meta-yocto
- poky is the *reference distro* provided by the Yocto Project
- meta-poky is the layer providing the poky reference distribution
The Yocto Project lexicon

- The Yocto Project is **not used as** a finite set of layers and tools.
- Instead, it provides a **common base** of tools and layers on top of which custom and specific layers are added, depending on your target.
Example of a Yocto Project based BSP

To build images for a BeagleBone Black, we need:

- The Poky reference system, containing all common recipes and tools.
- The *meta-ti-bsp* layer, a set of Texas Instruments specific recipes.

All modifications are made in your own layer. Editing Poky or *meta-ti* is a **no-go**!

We will set up this environment in the lab.
The Poky reference system overview
Getting the Poky reference system

- All official projects part of the Yocto Project are available at [https://git.yoctoproject.org/](https://git.yoctoproject.org/)

- To download the Poky reference system:
  ```
git clone -b kirkstone https://git.yoctoproject.org/git/poky
  ```

- A new version is released every 6 months, and maintained for 7 months

- **LTS** versions are maintained for 2 years, and announced before their release.

- Each release has a codename such as `kirkstone` or `honister`, corresponding to a release number.
  - A summary can be found at [https://wiki.yoctoproject.org/wiki/Releases](https://wiki.yoctoproject.org/wiki/Releases)
bitbake/  Holds all scripts used by the BitBake command. Usually matches the stable release of the BitBake project.

documentation/  All documentation sources for the Yocto Project documentation. Can be used to generate nice PDFs.

meta/  Contains the OpenEmbedded-Core metadata.

meta-skeleton/  Contains template recipes for BSP and kernel development.
meta-poky/  Holds the configuration for the Poky reference distribution.
meta-yocto-bsp/  Configuration for the Yocto Project reference hardware board support package.
LICENSE  The license under which Poky is distributed (a mix of GPLv2 and MIT).
oe-init-build-env  Script to set up the OpenEmbedded build environment. It will create the build directory.
scripts/  Contains scripts used to set up the environment, development tools, and tools to flash the generated images on the target.
Documentation

- Documentation for the current sources, compiled as a "mega manual", is available at: https://docs.yoctoproject.org/singleindex.html
- Variables in particular are described in the variable glossary: https://docs.yoctoproject.org/genindex.html
Using Yocto Project - basics
Environment setup
Environment setup

- All Poky files are left unchanged when building a custom image.
- Specific configuration files and build repositories are stored in a separate build directory.
- A script, `oe-init-build-env`, is provided to set up the build directory and the environment variables (needed to be able to use the `bitbake` command for example).
Modifies the environment: has to be sourced!

Adds environment variables, used by the build engine.

Allows you to use commands provided in Poky.

```
source ./oe-init-build-env [builddir]
```

Sets up a basic build directory, named `builddir` if it is not found. If not provided, the default name is `build`. 
Common targets are listed when sourcing the script:

- **core-image-minimal**  A small image to boot a device and have access to core command line commands and services.
- **core-image-sato**  Image with Sato support. Sato is a GNOME mobile-based user interface.
- **meta-toolchain**  Generates the cross-toolchain in an installable format.
- **meta-ide-support**  Generates the cross-toolchain and additional tools (gdb, qemu, ...) for IDE integration.
Exported environment variables

**BUILDDIR**  Absolute path of the build directory.

**PATH**  Contains the directories where executable programs are located. Absolute paths to `scripts/` and `bitbake/bin/` are prepended.
Available commands

**bitbake**  The main build engine command. Used to perform tasks on available recipes (download, configure, compile...).

**bitbake-** Various specific commands related to the BitBake build engine.
The build/ directory 1/2

- **conf/** Configuration files. Image specific and layer configuration.
- **downloads/** Downloaded upstream tarballs of the recipes used in the builds.
- **sstate-cache/** Shared state cache. Used by all builds.
- **tmp/** Holds all the build system outputs.
The build/ directory 2/2

tmp/work/  Set of specific work directories, split by architecture. They are used to unpack, configure and build the packages. Contains the patched sources, generated objects and logs.

tmp/sysroots/  Shared libraries and headers used to compile applications for the target but also for the host.

tmp/deploy/  Final output of the build.

tmp/deploy/images/  Contains the complete images built by the OpenEmbedded build system. These images are used to flash the target.

tmp/buildstats/  Build statistics for all packages built (CPU usage, elapsed time, host, timestamps...).
Configuring the build system
The `conf/` directory in the `build` one holds build specific configuration.

- **bblayers.conf**: Explicitly list the layers to use.
- **local.conf**: Set up the configuration variables relative to the current user for the build. Configuration variables can be overridden there.
The `conf/local.conf` configuration file holds local user configuration variables:

**BB_NUMBER_THREADS** How many tasks BitBake should perform in parallel. Defaults to the number of CPU threads on the system.

**PARALLEL_MAKE** How many processes should be used when compiling. Defaults to the number of CPU threads on the system.

**MACHINE** The machine the target is built for, e.g. beaglebone.
Building an image
The compilation is handled by the BitBake *build engine*.

**Usage:** `bitbake [options] [recipename/target ...]`

**To build a target:** `bitbake [target]`

**Building a minimal image:** `bitbake core-image-minimal`
  
  - This will run a full build for the selected target.
Practical lab - First Yocto build

- Download the sources
- Set up the environment
- Configure the build
- Build an image
Using Yocto Project - advanced usage

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Corrections, suggestions, contributions and translations are welcome!

embedded Linux and kernel engineering
Variable operators and overrides.
Select package variants.
Manually add packages to the generated image.
Run specific tasks with BitBake.
A Recipe describe how to fetch, configure, compile and install a software component (application, library, ...).

These tasks can be run independently (if their dependencies are met).

All the available packages in the project layer are not selected by default to be built and included in the images.

Some packages may provide the same functionality, e.g. OpenSSH and Dropbear.
Variables
The OpenEmbedded build system uses configuration variables to hold information.

Variable names are in upper-case by convention, e.g. CONF_VERSION

Variable values are strings

To make configuration easier, it is possible to prepend, append or define these variables in a conditional way.

Variables defined in Configuration Files have a global scope
  - Files ending in .conf

Variables defined in Recipes have a local scope
  - Files ending in .bb, .bbappend and .bbclass

Recipes can also access the global scope

All variables can be overridden or modified in $BUILDDIR/conf/local.conf
Various operators can be used to assign values to configuration variables:

- `=` expand the value when using the variable
- `:=` immediately expand the value
- `+=` append (with space)
- `==` prepend (with space)
- `.=` append (without space)
- `.=` prepend (without space)
- `?=` assign if no other value was previously assigned
- `??=` same as previous, with a lower precedence
Operators caveats

- The operators apply their effect during parsing
- Example:

```
VAR ?= "a"
VAR += "b"
```

Result: `VAR = "a b"

```
VAR += "b"
VAR ?= "a"
```

Result: `VAR = "b"

- The parsing order of files is difficult to predict, no assumption should be made about it.
- To avoid the problem, avoid using `+=`, `=+`, `.=` and `.=` in 
  `$BUILDDIR/conf/local.conf`. Always use overrides (see following slides).
Bitbake **overrides** allow appending, prepending or modifying a variable at expansion time, when the variable’s value is read.

Overrides are written as `<VARIABLE>:<override> = "some_value"`

A different syntax was used before **Honister**, with no retrocompatibility:

`<VARIABLE>_<override> = "some_value"`
Overrides to modify variable values

- **The append override adds at the end** of the variable (without space).
  - `IMAGE_INSTALL:append = " dropbear"` adds `dropbear` to the packages installed on the image.

- **The prepend override adds at the beginning** of the variable (without space).
  - `FILESEXTRAPATHS:prepend := "${THISDIR}/${PN}:"` adds the folder to the set of paths where files are located (in a recipe).

- **The remove override removes all occurrences** of a value within a variable.
  - `IMAGE_INSTALL:remove = "i2c-tools"`
Overrides for conditional assignment

▶ Append the machine name to only define a configuration variable for a given machine.
▶ It tries to match with values from OVERRIDES which includes MACHINE, SOC_FAMILY, and more.
▶ If the override is in OVERRIDES, the assignment is applied, otherwise it is ignored.

```
OVERRIDES="arm:armv7a:ti-soc:ti33x:beaglebone:poky"
KERNEL_DEVICETREE:beaglebone = "am335x-bone.dtbo" # This is applied
KERNEL_DEVICETREE:dra7xx-evm = "dra7-evm.dtbo"    # This is ignored
```
Overrides for conditional assignment: precedence

- The most specific assignment takes precedence.

- Example:
  
  IMAGE_INSTALL:beaglebone = "busybox mtd-utils i2c-tools"
  IMAGE_INSTALL = "busybox mtd-utils"

- If the machine is beaglebone:
  - IMAGE_INSTALL = "busybox mtd-utils i2c-tools"

- Otherwise:
  - IMAGE_INSTALL = "busybox mtd-utils"
The previous methods can be combined.

If we define:

- `IMAGE_INSTALL = "busybox mtd-utils"
- `IMAGE_INSTALL:append = " dropbear"
- `IMAGE_INSTALL:append:beaglebone = " i2c-tools"

The resulting configuration variable will be:

- `IMAGE_INSTALL = "busybox mtd-utils dropbear i2c-tools"` if the machine being built is beaglebone.
- `IMAGE_INSTALL = "busybox mtd-utils dropbear"` otherwise.
Order of variable assignment

1. All the operators are applied, in parsing order
2. :append overrides are applied
3. :prepend overrides are applied
4. :remove overrides are applied
Packages variants
Some packages have the same purpose, and only one can be used at a time.

The build system uses virtual packages to reflect this. A virtual package describes functionalities and several packages may provide it.

Only one of the packages that provide the functionality will be compiled and integrated into the resulting image.
Variant examples

- The virtual packages are often in the form `virtual/<name>`

- Example of available virtual packages with some of their variants:
  - `virtual/bootloader`: u-boot, u-boot-ti-staging...
  - `virtual/kernel`: linux-yocto, linux-yocto-tiny, linux-yocto-rt, linux-ti-staging...
  - `virtual/libc`: glibc, musl, newlib
  - `virtual/xserver`: xserver-xorg
Variants are selected thanks to the PREFERRED_PROVIDER configuration variable.

The package names **have to** suffix this variable.

Examples:

- PREFERRED_PROVIDER_virtual/kernel ?= "linux-ti-staging"
- PREFERRED_PROVIDER_virtual/libgl = "mesa"
By default, Bitbake will try to build the provider with the highest version number, from the highest priority layer, unless the recipe defines

```
DEFAULT_PREFERENCE = "-1"
```

When multiple package versions are available, it is also possible to explicitly pick a given version with `PREFERRED_VERSION`.

The package names have to suffix this variable.

% can be used as a wildcard.

Example:

- `PREFERRED_VERSION_nginx = "1.20.1"
- `PREFERRED_VERSION_linux-yocto = "5.14%"`
Packages
The set of packages installed into the image is defined by the target you choose (e.g. `core-image-minimal`).

It is possible to have a custom set by defining our own target, and we will see this later.

When developing or debugging, adding packages can be useful, without modifying the recipes.

Packages are controlled by the `IMAGE_INSTALL` configuration variable.
Exclusion

▶ The list of packages to install is also filtered using the `PACKAGE_EXCLUDE` variable.
▶ If you choose to not install a package using this variable and some other package is dependent on it (i.e. listed in a recipe’s RDEPENDS variable), the OpenEmbedded build system generates a fatal installation error.
▶ This only works with RPM and IPK packages.
The power of BitBake
Common BitBake options

- BitBake can be used to run a full build for a given target with `bitbake [target]`
  - `target` is a recipe name, possibly with modifiers, e.g. `-native`
  - `bitbake ncurses`
  - `bitbake ncurses-native`

- But it can be more precise, with optional options:
  - `-c <task>` execute the given task
    - `-s` list all locally available recipes and their versions
    - `-f` force the given task to be run by removing its stamp file
  - `world` keyword for all recipes
  - `-b <recipe>` execute tasks from the given recipe (without resolving dependencies).
BitBake examples

▶ `bitbake -c listtasks virtual/kernel`
  * Gives a list of the available tasks for the recipe providing the package virtual/kernel. Tasks are prefixed with `do_`.

▶ `bitbake -c menuconfig virtual/kernel`
  * Execute the task `menuconfig` on the recipe providing the virtual/kernel package.

▶ `bitbake -f dropbear`
  * Force the dropbear recipe to run all tasks.

▶ `bitbake --runall=fetch core-image-minimal`
  * Download all recipe sources and their dependencies.

▶ For a full description: `bitbake --help`
BitBake stores the output of each task in a directory, the shared state cache. Its location is controlled by the SSTATE_DIR variable.

This cache is used to speed up compilation.

Over time, as you compile more recipes, it can grow quite big. It is possible to clean old data with:

```bash
$ ../poky/scripts/sstate-cache-management.sh -y -d \
--cache-dir=sstate-cache/
```
Practical lab - Advanced Yocto configuration

- Modify the build configuration
- Customize the package selection
- Experiment with BitBake
- Mount the root file system over NFS
Recipes: overview
Basics

- A recipe describes how to handle a given software component (application, library, ...).
- It is a set of instructions to describe how to retrieve, patch, compile, install and generate binary packages.
- It also defines what build or runtime dependencies are required.
- Recipes are parsed by the BitBake build engine.
- The format of a recipe file name is `<application-name>_<version>.bb`
A recipe contains configuration variables: name, license, dependencies, path to retrieve the source code...

It also contains functions that can be run (fetch, configure, compile...) which are called **tasks**.

Tasks provide a set of actions to perform.

Remember the `bitbake -c <task> <target>` command?
To make it easier to write a recipe, some variables are automatically available:

- **PN**: package name, as specified in the recipe file name
- **BPN**: PN with prefixes and suffixes removed such as `nativesdk-`, or `-native`
- **PV**: package version, as specified in the recipe file name
- **BP**: defined as `${BPN}-${PV}`

The recipe name and version usually match the upstream ones.

When using the recipe `bash_5.1.bb`:

- `${PN} = "bash"
- `${PV} = "5.1"`
Organization of a recipe
Organization of a recipe

Poky

- meta/recipes-core/init-ifupdown/
  - init-ifupdown_1.0.bb

meta-custom

- recipes-core/init-ifupdown/
  - init-ifupdown_1.0.bbappend

meta-ti-bsp

- recipes-bsp/u-boot
  - u-boot_2014.07.bb

recipes-bsp/u-boot

- u-boot_custom.bb
  - u-boot_2014.07.bbappend
Many applications have more than one recipe, to support different versions. In that case the common metadata is included in each version specific recipe and is in a `.inc` file:

- `<application>.inc`
  - version agnostic metadata
- `<application>_<version>.bb`
  - require `<application>.inc`
  - any version specific metadata

We can divide a recipe into three main parts:

- The header: what/who
- The sources: where
- The tasks: how
Configuration variables to describe the application:

- **DESCRIPTION** describes what the software is about
- **HOMEPAGE** URL to the project's homepage
- **PRIORITY** defaults to optional
- **SECTION** package category (e.g. console/utils)
- **LICENSE** the application’s license, using SPDX identifiers ([https://spdx.org/licenses/](https://spdx.org/licenses/))
We need to retrieve both the raw sources from an official location and the resources needed to configure, patch or install the application.

**SRC_URI** defines where and how to retrieve the needed elements. It is a set of URI schemes pointing to the resource locations (local or remote).

**URI scheme syntax:** `scheme://url;param1;param2`

- `scheme` can describe a local file using `file://` or remote locations with `https://`, `git://`, `svn://`, `hg://`, `ftp://`...

By default, sources are fetched in `$BUILDDIR/downloads`. Change it with the `DL_DIR` variable in `conf/local.conf`
The source locations: remote files 1/2

The git scheme:
- `git://<url>;protocol=<protocol>;branch=<branch>`
- When using git, it is necessary to also define `SRCREV`. It has to be a commit hash and not a tag to be able to do offline builds. The `branch` parameter is mandatory unless `nobranch=1` is used.

The http, https and ftp schemes:
- `https://example.com/application-1.0.tar.bz2`
- A few variables are available to help pointing to remote locations: `${SOURCEFORGE_MIRROR}`, `${GNU_MIRROR}`, `${KERNELORG_MIRROR}`...
- Example: `${SOURCEFORGE_MIRROR}/<project-name>/${BPN}-${PV}.tar.gz`
- See `meta/conf/bitbake.conf`
The source locations: remote files 2/2

▶ An md5 or an sha256 sum must be provided when the protocol used to retrieve the file(s) does not guarantee their integrity. This is the case for https, http or ftp.

```
SRC_URI[md5sum] = "97b2c3fb082241ab5c56ab728522622b"
SRC_URI[sha256sum] = "..."
```

▶ It’s possible to use checksums for more than one file, using the name parameter:

```
SRC_URI = "http://example.com/src.tar.bz2;name=tarball \
          http://example.com/fixes.patch;name=patch"
```

```
SRC_URI[tarball.md5sum] = "97b2c3fb082241ab5c56..."
SRC_URI[patch.md5sum] = "b184acf9eb39df794ffd..."
```
The source locations: local files

- **SRC_URI** items using the file:// scheme are *local files*
- They are not downloaded, but rather copied from the layer to the work directory
- The searched paths are defined in the **FILESPATH** variable
- **FILESPATH** is a colon-separated list of paths to look for files
- The order matters: when a file is found in a paths, the search ends
FILESPATH is generated with all combinations of:

- **Base paths**
  - `${FILE_DIRNAME}/${BP}` (e.g. BP = dropbear-2020.81)
  - `${FILE_DIRNAME}/${BPN}` (e.g. BPN = dropbear)
  - `${FILE_DIRNAME}/files`
  - **Items in FILESEXTRAPATHS** (none by default)
  - `${FILE_DIRNAME}` is the directory containing the `.bb` file

- **The overrides in FILESOVERRIDES**
  - **Set as** `${TRANSLATED_TARGET_ARCH}:${MACHINEOVERRIDES}:${DISTROOVERRIDES}`
  - **E.g.** arm:armv7a:ti-soc:ti33x:beaglebone:poky
  - **Applied** right to left
This results in a long list, including:

- /.../meta/recipes-core/dropbear/dropbear-2020.81/poky
- /.../meta/recipes-core/dropbear/dropbear/poky
- /.../meta/recipes-core/dropbear/files/poky
- /.../meta/recipes-core/dropbear/dropbear-2020.81/beaglebone
- /.../meta/recipes-core/dropbear/dropbear/beaglebone
- /.../meta/recipes-core/dropbear/files/beaglebone
- /.../meta/recipes-core/dropbear/dropbear-2020.81/ti33x
- /.../meta/recipes-core/dropbear/dropbear/ti33x
- /.../meta/recipes-core/dropbear/files/ti33x
- ...
- /.../meta/recipes-core/dropbear/dropbear-2020.81/armv7a
- /.../meta/recipes-core/dropbear/dropbear/armv7a
- /.../meta/recipes-core/dropbear/files/armv7a
- ...
- /.../meta/recipes-core/dropbear/dropbear-2020.81/
- /.../meta/recipes-core/dropbear/dropbear/
- /.../meta/recipes-core/dropbear/files/
This complex logic allows to use different files without conditional code.

Example: with a single item in \texttt{SRC\_URI}:

\begin{verbatim}
\texttt{SRC\_URI} += "file://defconfig"
\end{verbatim}

A different \texttt{defconfig} can be used for different \texttt{MACHINE} values:

\begin{verbatim}
recipes-kernel/
    linux
        my-linux
            mymachine1
                defconfig \texttt{<-- used when MACHINE="mymachine1"}
            mymachine2
                defconfig \texttt{<-- used when MACHINE="mymachine2"}
        defconfig \texttt{<-- used for any other MACHINE value}
    my-linux_6.4.bb
\end{verbatim}
When extracting a tarball, BitBake expects to find the extracted files in a directory named `<application>-<version>`. This is controlled by the `S` variable. If the directory has another name, you must explicitly define `S`.

If the scheme is `git`, `S` must be set to `${WORKDIR}/git`
The source locations: license files

- License files must have their own checksum.
- LIC_FILES_CHKSUM defines the URI pointing to the license file in the source code as well as its checksum.

```
LIC_FILES_CHKSUM = "file://gpl.txt;md5=393a5ca..."
LIC_FILES_CHKSUM = "file://main.c;beginline=3;endline=21;md5=58e..."
LIC_FILES_CHKSUM = "file://${COMMON_LICENSE_DIR}/MIT;md5=083..."
```

- This allows to track any license update: if the license changes, the build will trigger a failure as the checksum won’t be valid anymore.
A recipe can have dependencies during the build or at runtime. To reflect these requirements in the recipe, two variables are used:

**DEPENDS**  List of the recipe build-time dependencies.

**RDEPENDS**  List of the package runtime dependencies. Must be package specific (e.g. with :${PN}$).

**DEPENDS = "recipe-b":** the local do_prepare_recipe_sysroot task depends on the do_populate_sysroot task of recipe-b.

**RDEPENDS:${PN} = "package-b":** the local do_build task depends on the do_package_write_<archive-format> task of recipe b.
Sometimes a recipe has dependencies on specific versions of another recipe.

BitBake allows to reflect this by using:

- `DEPENDS = "recipe-b (>= 1.2)"
- `RDEPENDS:${PN} = "recipe-b (>= 1.2)"

The following operators are supported: =, >, <, >= and <=.

A graphical tool can be used to explore dependencies or reverse dependencies:

- `bitbake -g -u taskexp core-image-minimal`
Default tasks already exist, they are defined in classes:

- do_fetch
- do_unpack
- do_patch
- do_configure
- do_compile
- do_install
- do_package
- do_rootfs

You can get a list of existing tasks for a recipe with:

```
bitbake <recipe> -c listtasks
```
Functions use the sh shell syntax, with available OpenEmbedded variables and internal functions available.

- **WORKDIR** - the recipe’s working directory
- **S** - The directory where the source code is extracted
- **B** - The directory where bitbake places the objects generated during the build
- **D** - The destination directory (root directory of where the files are installed, before creating the image).

Syntax of a task:

```bash
do_task() {
    action0
    action1
    ...
}
```
Example:

do_compile() {
    oe_runmake
}

do_install() {
    install -d ${D}${bindir}
    install -m 0755 hello ${D}${bindir}
}
The main tasks
Adding new tasks

Tasks can be added with `addtask`

```c
do_mkimage () {
    uboot-mkimage ...
}
```

`addtask do_mkimage after do_compile before do_install`
Applying patches
Patches use cases

Patches can be applied to resolve build-system problematics:

▶ To support old versions of a software: bug and security fixes.
▶ To fix cross-compilation issues.
  • In certain simple cases the -e option of make can be used.
  • The -e option gives variables taken from the environment precedence over variables from Makefiles.
  • Helps when an upstream Makefile uses hardcoded CC and/or CFLAGS.
▶ To apply patches before they get their way into the upstream version.
The source locations: patches

- Files ending in `.patch`, `.diff` or having the `apply=yes` parameter will be applied after the sources are retrieved and extracted, during the `do_patch` task.

```
SRC_URI += "file://joystick-support.patch \
            file://smp-fixes.diff \n            "
```

- Patches are applied in the order they are listed in `SRC_URI`.
- It is possible to select which tool will be used to apply the patches listed in `SRC_URI` variable with `PATCHTOOL`.
- By default, `PATCHTOOL = 'quilt'` in Poky.
- Possible values: `git`, `patch` and `quilt`. 
The PATCHRESOLVE variable defines how to handle conflicts when applying patches.

- It has two valid values:
  - **noop**: the build fails if a patch cannot be successfully applied.
  - **user**: a shell is launched to resolve manually the conflicts.

- By default, PATCHRESOLVE = "noop" in meta-poky.
Example of a recipe
Hello world recipe

DESCRIPTION = "Hello world program"
HOMEPAGE = "http://example.net/hello/
PRIORITIY = "optional"
SECTION = "examples"
LICENSE = "GPL-2.0-or-later"
SRC_URI = "git://git.example.com/hello;protocol=https;branch=master"
SRCREV = "2d47b4eb66e705458a17622c2e09367300a7b118"
S = "${WORKDIR}/git"
LIC_FILES_CHKSUM = "file://hello.c;beginline=3;endline=21;md5=58e..."

do_compile() {
    oe_runmake
}
do_install() {
    install -d ${D}${bindir}
    install -m 0755 hello ${D}${bindir}
}

Hello world program
Example of a recipe with a version agnostic part
SUMMARY = "GNU file archiving program"
HOMEPAGE = "https://www.gnu.org/software/tar/"
SECTION = "base"

SRC_URI = "${GNU_MIRROR}/tar/tar-${PV}.tar.bz2"

do_configure() { ... }

do_compile() { ... }

do_install() { ... }
require tar.inc

LICENSE = "GPL-2.0-only"
LIC_FILES_CHKSUM = \
    "file://COPYING;md5=59530bdf33659b29e73d4adb9f9f6552"

SRC_URI += "file://avoid_heap_overflow.patch"

SRC_URI[md5sum] = "c6c4f1c075dbf0f75c29737faa58f290"
require tar.inc

LICENSE = "GPL-3.0-only"

LIC_FILES_CHKSUM = \ 
    "file://COPYING;md5=d32239bcb673463ab874e80d47fae504"

SRC_URI[md5sum] = "2cee42a2ff4f1cd4f9298eeeb2264519"
Practical lab - Add a custom application

- Write a recipe for a custom application
- Integrate it in the image
Extending a recipe
Introduction to recipe extensions

- It is a good practice to avoid modifying recipes available in third party layers so it is easy to update.
- But it is sometimes useful to apply a custom patch or add a configuration file for example.
- The BitBake *build engine* allows to modify a recipe by extending it.
- Multiple extensions can be applied to a recipe.
Introduction to recipe extensions

- Metadata can be changed, added or appended.
- Tasks can be added or appended.
- Operators are used extensively, to add, append, prepend or assign values.
Extend a recipe

- The recipe extensions end in `.bbappend`
- Append files must have the same root name as the recipe they extend, but can also use wildcards.
  - `example_0.1.bbappend` applies to `example_0.1.bb`
  - `example_0.%.bbappend` applies to `example_0.1.bb` and `example_0.2.bb` but not `example_1.0.bb`
- Append files should be **version specific**. If the recipe is updated to a newer version, the append files must also be updated.
- If adding new files, the path to their directory must be prepended to the `FILESEXTARAPATHS` variable.
  - Files are looked up in paths referenced in `FILESEXTARAPATHS`, from left to right.
  - Prepending a path makes sure it has priority over the recipe’s one. This allows to override recipes’ files.
FILESEXTRAPATHS:prepend := "${THISDIR}/files:"

SRC_URI += "file://custom-modification-0.patch \n    file://custom-modification-1.patch \n"
Modifying existing tasks

Tasks can be extended with :prepend or :append

do_install:append() {
    install -d ${D}${sysconfdir}
    install -m 0644 hello.conf ${D}${sysconfdir}
}
Providing virtual packages
Providing virtual packages

- BitBake allows to use virtual names instead of the actual package name. We saw a use case with *package variants*.
- The virtual name is specified through the `PROVIDES` variable.
- Several recipes can provide the same virtual name. Only one will be built and installed into the generated image.
- `PROVIDES = "virtual/kernel"`
Classes
Introduction to classes

- Classes provide an abstraction to common code, which can be re-used in multiple recipes.
- Common tasks do not have to be re-developed!
- Any metadata and task which can be put in a recipe can be used in a class.
- Classes extension is `.bbclass`
- Classes are located in the `classes` folder of a layer.
- Recipes can use this common code by inheriting a class:
  - `inherit <class>`
Common classes

- Common classes can be found in meta/classes/
  - base.bbclass
  - kernel.bbclass
  - autotools.bbclass
  - autotools-brokensep.bbclass
  - cmake.bbclass
  - meson.bbclass
  - native.bbclass
  - systemd.bbclass
  - update-rc.d.bbclass
  - useradd.bbclass
  - ...

- Kernel, drivers and embedded Linux - Development, consulting, training and support - https://bootlin.com
The base class

- Every recipe inherits the base class automatically.
- Defines basic common tasks with a default implementation:
  - fetch, unpack, patch
  - configure, compile, install
  - Utility tasks such as: clean, listtasks
- Automatically applies patch files listed in SRC_URI
- Defines mirrors: SOURCEFORGE_MIRROR, DEBIAN_MIRROR, GNU_MIRROR, KERNELORG_MIRROR...
- Defines oe_runmake, using EXTRA_OEMAKE to use custom arguments.
The kernel class

- Used to build Linux kernels.
- Defines tasks to configure, compile and install a kernel and its modules.
- Automatically applies a defconfig listed in SRC_URI

SRC_URI += "file://defconfig"

- The kernel is divided into several packages: kernel, kernel-base, kernel-dev, kernel-modules...
- Automatically provides the virtual package virtual/kernel.
- Configuration variables are available:
  - KERNEL_IMAGETYPE, defaults to zImage
  - KERNEL_EXTRA_ARGS
  - INITRAMFS_IMAGE
The autotools class

- Defines tasks and metadata to handle applications using the autotools build system (autoconf, automake and libtool):
  - do_configure: generates the configure script using autoreconf and loads it with standard arguments or cross-compilation.
  - do_compile: runs make
  - do_install: runs make install

- Extra configuration parameters can be passed with EXTRA_OECONF.
- Compilation flags can be added thanks to the EXTRA_OEMAKE variable.
Example: use the autotools class

DESCRIPTION = "Print a friendly, customizable greeting"
HOMEPAGE = "https://www.gnu.org/software/hello/
PRIORITY = "optional"
SECTION = "examples"
LICENSE = "GPL-3.0-or-later"

SRC_URI = "${GNU_MIRROR}/hello/hello-${PV}.tar.gz"
SRC_URI[md5sum] = "67607d2616a0faaf5bc94c59dca7c3cb"
SRC_URI[sha256sum] = "ecbb7a2214196c57ff9340aa71458e1559abd38f6d8d169666846935df191e7"
LIC_FILES_CHKSUM = "file://COPYING;md5=d32239bcb673463ab874e80d47fae504"

inherit autotools
The useradd class

- This class helps to add users to the resulting image.
- Adding custom users is required by many services to avoid running them as root.
- **USERADD_PACKAGES** must be defined when the useradd class is inherited. Defines the list of packages which needs the user.
- Users and groups will be created before the packages using it perform their do_install.
- At least one of the two following variables must be set:
  - **USERADD_PARAM**: parameters to pass to useradd.
  - **GROUPADD_PARAM**: parameters to pass to groupadd.
DESCRIPTION = "useradd class usage example"
PRIORITY = "optional"
SECTION = "examples"
LICENSE = "MIT"

SRC_URI = "file://file0"
LIC_FILES_CHKSUM = "file://${COREBASE}/meta/files/common-licenses/MIT;md5=0835ade698e0bc..."

inherit useradd

USERADD_PACKAGES = "${PN}"
USERADD_PARAM = "-u 1000 -d /home/user0 -s /bin/bash user0"

do_install() {
  install -m 644 file0 ${D}/home/user0/
  chown user0:user0 ${D}/home/user0/file0
}
The bin_package class

▶ In some cases you only need to install pre-built files into the generated root filesystem
  • E.g.: firmware blobs
▶ bin_package.bbclass simplifies this
  • Disables do_configure and do_compile
  • Provides a default do_install that copies whatever is in S (useful e.g. when extracting a pre-built RPM/DPKG)
▶ Additionally you probably need:
  • Remember to set the LICENSE to CLOSED if applicable
  • You probably should also inherit allarch
BitBake file inclusions
Locate files in the build system

- Metadata can be shared using included files.
- BitBake uses the BBPATH to find the files to be included. It also looks into the current directory.
- Three keywords can be used to include files from recipes, classes or other configuration files:
  - inherit
  - include
  - require
The *inherit* keyword

- *inherit* can be used in recipes or classes, to inherit the functionalities of a class.
- To inherit the functionalities of the *kernel* class, use: *inherit kernel*
- *inherit* looks for files ending in `.bbclass`, in `classes` directories found in `BBPATH`.
- It is possible to include a class conditionally using a variable: *inherit ${FOO}*
The include and require keywords

- **include and require** can be used in all files, to insert the content of another file at that location.

- If the path specified on the include (or require) path is relative, BitBake will insert the first file found in BBPATH.

- **include** does not produce an error when a file cannot be found, whereas **require** raises a parsing error.

- To include a local file: `require ninvaders.inc`

- To include a file from another location (which could be in another layer): `require path/to/file.inc`
Debugging recipes
For each task, logs are available in the temp directory in the work folder of a recipe. This includes both the actual tasks code that ran and the output of the task.

bitbake can dump the whole environment, including the variable values and how they were set:

```bash
$ bitbake -e ninvaders
# $DEPENDS [4 operations]
# set /yocto-labs/poky/meta/conf/bitbake.conf:268
# ""
# set /yocto-labs/poky/meta/conf/documentation.conf:130
# [doc] "Lists a recipe's build-time dependencies (i.e. other recipe files)."
# :prepend /yocto-training/yocto-labs/poky/meta/classes/base.bbclass:74
# "$\{BASEDEPENDS\}"
# set /yocto-labs/meta-bootlinlabs/recipes-games/ninvaders/ninvaders.inc:11
# "ncurses"
# pre-expansion value:
# ""$\{BASEDEPENDS\} ncurses"
DEPENDS="virtual/arm-poky-linux-gnueabi-gcc virtual/arm-poky-linux-gnueabi-compilerlibs virtual/libc ncurses"
```
A development shell, exporting the full environment can be used to debug build failures:

$ bitbake -c devshell <recipe>

To understand what a change in a recipe implies, you can activate build history in local.conf:

INHERIT += "buildhistory"
BUILDHISTORY_COMMIT = "1"

Then use the buildhistory-diff tool to examine differences between two builds.

• buildhistory-diff
Network usage
BitBake will look for files to retrieve at the following locations, in order:

1. `DL_DIR` (the local download directory).
2. The `PREMIRRORS` locations.
3. The upstream source, as defined in `SRC_URI`.
4. The `MIRRORS` locations.

If all the mirrors fail, the build will fail.
Mirror configuration in OpenEmbedded-Core

```
meta/classes/mirrors.bbclass

PREMIRRORS += "git://sourceware.org/git/glibc.git https://downloads.yoctoproject.org/mirror/sources/ \ 
git://sourceware.org/git/binutils-gdb.git https://downloads.yoctoproject.org/mirror/sources/"

MIRRORS += "\ 
svn://.*/.* http://sources.openembedded.org/ \ 
git://.*/.* http://sources.openembedded.org/ \ 
https?://.*/.* http://sources.openembedded.org/ \ 
ftp://.*/.* http://sources.openembedded.org/ \ 
..."
```
Configuring the premirrors

▶ It is easy to add a custom mirror to the PREMIRRORS by using the own-mirrors class (only one URL supported):

```
INHERIT += "own-mirrors"
SOURCE_MIRROR_URL = "http://example.com/my-mirror"
```

▶ For a more complex setup, prepend custom mirrors to the PREMIRRORS variable:

```
```
Forbidding network access

- You can use `BB_GENERATE_MIRROR_TARBALLS = "1"` to generate tarballs of the git repositories in `DL_DIR`
- You can also completely disable network access using `BB_NO_NETWORK = "1"
  - To download all the sources before disabling network access use:
    `bitbake --runall=fetch core-image-minimal`
- Or restrict BitBake to only download files from the `PREMIRRORS`, using `BB_FETCH_PREMIRRORONLY = "1"`
Introduction to layers
Layers’ principles

- The OpenEmbedded build system manipulates metadata.
- Layers allow to isolate and organize the metadata.
  - A layer is a collection of recipes.
- It is a good practice to begin a layer name with the prefix meta-.
Layers in Poky

OpenEmbedded Project

- Kernel, drivers and embedded Linux

- Development, consulting, training and support

- https://bootlin.com

Yocto Project

- Poky

- meta

- meta-skeleton

- scripts

- meta-poky

- meta-yocto-bsp

- BitBake

meta-ti-bsp

- recipes-bsp

- recipes-connectivity

- recipes-kernel

- recipes-ti

- recipes-core

- recipes-graphics

meta-qt5

- recipes-qt

- ...

meta-custom

- recipes

- ...

Entity

Layer

Recipes

ADT

Pseudo

Matchbox

Other
 Layers in Poky

- The Poky *reference system* is a set of basic common layers:
  - meta
  - meta-skeleton
  - meta-poky
  - meta-yocto-bsp

- Poky is not a final set of layers. It is the common base.
- Layers are added when needed.
- When making modifications to the existing recipes or when adding new ones, it is a good practice to avoid modifying Poky. Instead you can create your own layers!
Third party layers

[Diagram illustrating the relationship between OpenEmbedded Project, Yocto Project, and various layers and recipes, including meta, meta-poky, scripts, meta-yocto-bsp, BitBake, meta-ti-bsp, recipes-bsp, recipes-connectivity, recipes-kernel, meta-qt5, recipes-qt, recipes-ti, recipes-core, recipes-graphics, and meta-custom.]
Integrate and use a layer 1/3

- A list of existing and maintained layers can be found at https://layers.openembedded.org
- Instead of redeveloping layers, always check the work hasn’t been done by others.
- It takes less time to download a layer providing a package you need and to add an append file if some modifications are needed than to do it from scratch.
The location where a layer is saved on the disk doesn’t matter.
- But a good practice is to save it where all others layers are stored.

The only requirement is to let BitBake know about the new layer:
- The list of layers BitBake uses is defined in `$BUILDDIR/conf/bblayers.conf`
- To include a new layer, add its absolute path to the `BBLAYERS` variable.
- BitBake parses each layer specified in `BBLAYERS` and adds the recipes, configurations files and classes it contains.
Integrate and use a layer 3/3

- The **bitbake-layers** tool is provided alongside **bitbake**.
- It can be used to inspect the layers and to manage
  
  ```
  $BUILDDIR/conf/bblayers.conf:
  ```
  
  - `bitbake-layers show-layers`
  - `bitbake-layers add-layer meta-custom`
  - `bitbake-layers remove-layer meta-qt5`
Some useful layers

- Many SoC specific layers are available, providing support for the boards using these SoCs. Some examples: meta-ti, meta-freescale and meta-raspberrypi.

- Other layers offer to support applications not available in the Poky reference system:
  - meta-browser: web browsers (Chromium, Firefox).
  - meta-filesystems: support for additional filesystems.
  - meta-gstreamer10: support for GStreamer 1.0.
  - meta-java and meta-oracle-java: Java support.
  - meta-linaro-toolchain: Linaro toolchain recipes.
  - meta-qt5: QT5 modules.
  - meta-realtime: real time tools and test programs.
  - meta-telephony and many more...

Notice that some of these layers do not come with all the Yocto branches. The meta-browser did not have a krogoth branch, for example.
Creating a layer
Custom layer

OpenEmbedded Project

- OpenEmbedded Core
  - meta
    - recipes-core
    - recipes-bsp
    - recipes-connectivity
    - recipes-kernel
  - scripts

Yocto Project

- Poky
  - meta-skeleton
  - meta-poky
  - meta-yocto-bsp

- BitBake

Other

- meta-custom
  - recipes
  - ...

Entity

Layer

Recipes

Other
Create a custom layer 1/2

- A layer is a set of files and directories and can be created by hand.
- However, the `bitbake-layers create-layer` command helps us create new layers and ensures this is done right.
- `bitbake-layers create-layer -p <PRIORITY> <layer>`
- The **priority** is used to select which recipe to use when multiple layers contain the same recipe.
- The recipe priority takes precedence over the version number ordering.
Create a custom layer 2/2

The layer created will be pre-filled with the following files:

- **conf/layer.conf**  The layer’s configuration. Holds its priority and generic information. No need to modify it in many cases.
- **COPYING.MIT**  The license under which a layer is released. By default MIT.
- **README**  A basic description of the layer. Contains a contact e-mail to update.

By default, all metadata matching `.*/recipes-*/*/*.bb` will be parsed by the BitBake build engine.
Use a layer: best practices

▶ Do not copy and modify existing recipes from other layers. Instead use append files.
▶ Avoid duplicating files. Use append files or explicitly use a path relative to other layers.
▶ Save the layer alongside other layers.
▶ Use LAYERDEPENDS to explicitly define layer dependencies.
▶ Use LAYERSERIES_COMPAT to define the Yocto version(s) with which the layer is compatible.
Practical lab - Create a custom layer

- Create a layer from scratch
- Add recipes to the new layer
- Integrate it to the build
Practical lab - Extend a recipe

- Apply patches to an existing recipe
- Use a custom configuration file for an existing recipe
- Extend a recipe to fit your needs
BSP Layers

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Introduction to BSP layers in the Yocto Project
BSP layers

- Kernel, drivers and embedded Linux - Development, consulting, training and support - https://bootlin.com
BSP layers overview

- BSP layers are a subset of the layers.
- They hold metadata with the purpose of supporting a specific class of hardware devices.
- They usually provide:
  - Hardware configuration files (machines)
  - Custom kernel and bootloader recipes and configurations
  - Modules and drivers to enable specific hardware features (e.g. multimedia accelerators)
  - Pre-built user binaries and firmwares
- A good practice is to name it `meta-<bsp_name>`.
Hardware configuration files
A layer provides one machine file (hardware configuration file) per machine it supports.

These configuration files are stored under
`meta-<bsp_name>/conf/machine/*.conf`

The file names correspond to the values set in the `MACHINE` configuration variable.

- `meta-ti/meta-ti-bsp/conf/machine/beaglebone.conf`
- `MACHINE = "beaglebone"`

Each machine should be described in the `README` file of the BSP.
The hardware configuration file contains configuration variables related to the architecture and to the machine features.

Some other variables help customize the kernel image or the filesystems used.
Machine configuration

TARGET_ARCH  The architecture of the device being built.
PREFERRED_PROVIDER_virtual/kernel  The default kernel.
MACHINE_FEATURES  List of hardware features provided by the machine, e.g.
                         usbgadget usbhost screen wifi
SERIAL_CONSOLES  Speed and device for the serial console to attach. Used to
                         configure getty, e.g. 115200;ttyS0
KERNEL_IMAGETYPE  The type of kernel image to build, e.g. zImage
Lists the hardware features provided by the machine.

These features are used by package recipes to enable or disable functionalities.

Some packages are automatically added to the resulting root filesystem depending on the feature list.

The feature **bluetooth**:

- Asks the **bluez** daemon to be built and added to the image.
- Enables bluetooth support in **ConnMan**.
# Common definitions for cfa-10036 boards

include conf/machine/include/imx-base.inc
include conf/machine/include/tune-arm926ejs.inc

SOC_FAMILY = "mxs:mx28:cfa10036"

PREFERRED_PROVIDER_virtual/kernel ?= "linux-cfa"
PREFERRED_PROVIDER_virtual/bootloader ?= "barebox"
IMAGE_BOOTLOADER = "barebox"
BAREBOX_BINARY = "barebox"
IMAGE_FSTYPES:mxs = "tar.bz2 barebox.mxsboot-sdcard sdcard.gz"
IMXBOOTLETS_MACHINE = "cfa10036"

KERNEL_imagETYPE = "zImage"
KERNEL_DEVICETREE = "imx28-cfa10036.dtb"

# we need the kernel to be installed in the final image
IMAGE_INSTALL:append = " kernel-image kernel-devicetree"

SDCARD_ROOTFS ?= "${DEPLOY_DIR_IMAGE}/${IMAGE_NAME}.rootfs.ext3"
SERIAL_CONSOLE = "115200 ttyAMA0"
MACHINE_FEATURES = "usbgadget usbhost vfat"
#TYPE: Machine
#NAME: Crystalfontz CFA-10057
#SOC: i.MX28
#DESCRIPTION: Machine configuration for CFA-10057, also called CFA-920
#MAINTAINER: Alexandre Belloni <alexandre.belloni@bootlin.com>

include conf/machine/include/cfa10036.inc

KERNEL_DEVICETREE += "imx28-cfa10057.dtb"

MACHINE_FEATURES += "touchscreen"
Bootloader
By default the bootloader used is the mainline version of U-Boot, with a fixed version (per Poky release).

All the magic is done in `meta/recipes-bsp/u-boot/u-boot.inc`

Some configuration variables used by the U-Boot recipe can be customized, in the machine file.
SPL_BINARY If an SPL is built, describes the name of the output binary. Defaults to an empty string.

UBOOT_SUFFIX bin (default) or img.

UBOOT_MACHINE The target used to build the configuration.

UBOOT_ENTRYPOINT The bootloader entry point.

UBOOT_LOADADDRESS The bootloader load address.

UBOOT_MAKE_TARGET Make target when building the bootloader. Defaults to all.
It is possible to support a custom U-Boot by creating an extended recipe and to append extra metadata to the original one.

This works well when using a mainline version of U-Boot.

Otherwise it is possible to create a custom recipe.

* Try to still use `meta/recipes-bsp/u-boot/u-boot.inc`
Kernel
There are mainly two ways of compiling a kernel:

- By creating a custom kernel recipe, inheriting `kernel.bbclass`
- By using the `linux-yocto` packages, provided in Poky, for very complex needs

The kernel used is selected in the machine file thanks to:

```
PREFERRED_PROVIDER_virtual/kernel
```

Its version is defined with:

```
PREFERRED_VERSION_<kernel_provider>
```
- Linux Yocto 1/3

- **linux-yocto** is a set of recipes with advanced features to build a mainline kernel
- **PREFERRED_PROVIDER_virtual/kernel** = "linux-yocto"
- **PREFERRED_VERSION_linux-yocto** = "5.14%"
Automatically applies configuration fragments listed in SRC_URI with a .cfg extension

```
SRC_URI += "file://defconfig \nfile://nand-support.cfg \nfile://ethernet-support.cfg"
```
Another way of configuring **linux-yocto** is by using *Advanced Metadata*.

It is a powerful way of splitting the configuration and the patches into several pieces.

It is designed to provide a very configurable kernel, at the cost of higher complexity.

The full documentation can be found at [https://docs.yoctoproject.org/kernel-dev/advanced.html#working-with-advanced-metadata-yocto-kernel-cache](https://docs.yoctoproject.org/kernel-dev/advanced.html#working-with-advanced-metadata-yocto-kernel-cache)
Kernel Metadata is a way to organize and to split the kernel configuration and patches in little pieces each providing support for one feature.

Two main configuration variables help taking advantage of this:

- **LINUX_KERNEL_TYPE** standard (default), tiny or preempt-rt
  - standard: generic Linux kernel policy.
  - tiny: bare minimum configuration, for small kernels.
  - preempt-rt: applies the PREEMPT_RT patch.

- **KERNEL_FEATURES** List of features to enable. Features are sets of patches and configuration fragments.
Kernel Metadata description files have their own syntax to describe an optional kernel feature.

A basic feature is defined as a patch to apply and a configuration fragment to add.

Simple example, features/nunchuk.scc

```
define KFEATURE_DESCRIPTION "Enable Nunchuk driver"

kconf hardware enable-nunchuk-driver.cfg
patch Add-nunchuk-driver.patch
```

To integrate the feature into the kernel image:
```
KERNEL_FEATURES += "features/nunchuk.scc"
```
Practical lab - Create a custom machine configuration

- Write a machine configuration
- Understand how the target architecture is chosen
Distro Layers

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Distro Layers

Distro Layers
Distro layers

OpenEmbedded Project

- meta
  - recipes-core
  - recipes-bsp
  - recipes-connectivity
  - recipes-kernel

Yocto Project

- Poky
  - meta-skeleton
  - meta-yocto-bsp
  - scripts

- meta-poky

- BitBake

meta-ti-bsp

- recipes-bsp
- recipes-connectivity
- recipes-kernel
- recipes-ti
- recipes-core
- recipes-graphics

meta-qt5

- recipes-qt
- recipes

meta-custom

- recipes
You can create a new distribution by using a Distro layer.

This allows to change the defaults that are provided by openembedded-core or poky.

It is useful to distribute changes that have been made in local.conf.
Best practice

- A distro layer is used to provide policy configurations for a custom distribution.
- It is a best practice to separate the distro layer from the custom layers you may create and use.
- It often contains:
  - Configuration files.
  - Specific classes.
  - Distribution specific recipes: initialization scripts, splash screen...
Creating a Distro layer

- The configuration file for the distro layer is `conf/distro/<distro>.conf`
- This file must define the `DISTRO` variable.
- It is possible to inherit configuration from an existing distro layer.
- You can also use all the `DISTRO_*` variables.
- Use `DISTRO = "<distro>"` in `local.conf` to use your distro configuration.

```plaintext
require conf/distro/poky.conf

DISTRO = "distro"
DISTRO_NAME = "distro description"
DISTRO_VERSION = "1.0"
MAINTAINER = "..."
```
DISTRO_FEATURES

- Lists the features the distribution will provide.
- As for MACHINE_FEATURES, this is used by package recipes to enable or disable functionalities.
- COMBINED_FEATURES provides the list of features that are enabled in both MACHINE_FEATURES and DISTRO_FEATURES.
Toolchain selection

- The toolchain selection is controlled by the `TCMODE` variable.
- It defaults to "default".
- The `conf/distro/include/tcmode-${TCMODE}.inc` file is included.
  - This configures the toolchain to use by defining preferred providers and versions for recipes such as `gcc`, `binutils`, `*libc`...
- The providers’ recipes define how to compile or/and install the toolchain.
- Toolchains can be built by the build system or external.
A distro layer often contains sample files, used as templates to build key configurations files.

Example of sample files:
- bblayers.conf.sample
- local.conf.sample

In Poky, they are in meta-poky/conf/.

The TEMPLATECONF variable controls where to find the samples.

It is set in `${OEROOT}/.templateconf`.
- OEROOT is the directory that contains the oe-init-build-env script.
Introduction to images
An image is the top level recipe and is used alongside the machine definition.

Whereas the machine describes the hardware used and its capabilities, the image is architecture agnostic and defines how the root filesystem is built, with what packages.

By default, several images are provided in Poky:

- meta*/recipes*/images/*.bb
Common images are:

- **core-image-base**: Console-only image, with full support of the hardware.
- **core-image-minimal**: Small image, capable of booting a device.
- **core-image-minimal-dev**: Small image with extra tools, suitable for development.
- **core-image-x11**: Image with basic X11 support.
- **core-image-rt**: `core-image-minimal` with real time tools and test suite.
An image is no more than a recipe.

It has a description, a license and inherits the core-image class.
Some special configuration variables are used to describe an image:

**IMAGE_BASENAME**  The name of the output image files. Defaults to `${PN}`.

**IMAGE_INSTALL**  List of packages and package groups to install in the generated image.

**IMAGE_ROOTFS_SIZE**  The final root filesystem size.

**IMAGE_FEATURES**  List of features to enable in the image.

**IMAGE_FSTYPES**  List of formats the OpenEmbedded build system will use to create images.

**IMAGE_LINGUAS**  List of the locales to be supported in the image.

**IMAGE_PKGTYPE**  Package type used by the build system. One of `deb`, `rpm`, `ipk` and `tar`.

**IMAGE_POSTPROCESS_COMMAND**  Shell commands to run at post process.

**EXTRA_IMAGEDEPENDS**  Recipes to be built with the image, but which do not install anything in the root filesystem (e.g. the bootloader).
require recipes-core/images/core-image-minimal.bb

DESCRIPTION = "Example image"

IMAGE_INSTALL += "ninvaders"

LICENSE = "MIT"
Root filesystem generation

- Image generation overview:
  1. An empty directory is created for the root filesystem.
  2. Packages from `IMAGE_INSTALL` are installed into it using the package manager.
  3. One or more images files are created, depending on the `IMAGE_FSTYPES` value.

- The rootfs creation is specific to the `IMAGE_PKGTYPE` value. It should be defined in the image recipe, otherwise the first valid package type defined in `PACKAGE_CLASSES` is used.

- All the magic is done in `meta/classes/rootfs_${IMAGE_PKGTYPE}.bbclass`
Images

Image types
Configures the resulting root filesystem image format.

If more than one format is specified, one image per format will be generated.

Image formats instructions are provided by openembedded-core, in meta/classes/image_types.bbclass

Common image formats are: ext2, ext3, ext4, squashfs, squashfs-xz, cpio, jffs2, ubifs, tar.bz2, tar.gz...
If you have a particular layout on your storage (for example bootloader location on an SD card), you may want to create your own image type.

This is done through a class that inherits from `image_types`.

It has to define a function named `IMAGE_CMD:<type>`.

Append it to `IMAGE_TYPES`
Creating an image conversion type

- Common conversion types are: gz, bz2, sha256sum, bmap...
- This is done through a class that inherits from `image_types`.
- It has to define a function named `CONVERSION_CMD:<type>`.
- Append it to `CONVERSIONTYPES`.
- Append valid combinations to `IMAGETYPES`.
wic is a tool that can create a flashable image from the compiled packages and artifacts.

- It can create partitions.
- It can select which files are located in which partition through the use of plugins.
- The final image layout is described in a .wks or .wks.in file.
- It can be extended in any layer.

Usage example:

```plaintext
WKS_FILE = "imx-uboot-custom.wks.in"
IMAGE_FSTYPES = "wic.bmap wic"
```
part u-boot --source rawcopy --sourceparams="file=imx-boot" --no-table --align ${IMX_BOOT_SEEK}
part /boot --source bootimg-partition --use-uuid --fstype=vfat --label boot --active --align 8192 --size 64
part / --source rootfs --use-uuid --fstype=ext4 --label root --exclude-path=home/ --exclude-path=opt/ --align 8192
part /home --source rootfs --rootfs-dir=${IMAGE_ROOTFS}/home --use-uuid --fstype=ext4 --label home --align 8192
part /opt --source rootfs --rootfs-dir=${IMAGE_ROOTFS}/opt --use-uuid --fstype=ext4 --label opt --align 8192
bootloader --ptable msdos

▶ Copies **imx-boot** from `$DEPLOY_DIR` in the image, aligned on (and so at that offset) `${IMX_BOOT_SEEK}`.

▶ Creates a first partition, formatted in FAT32, with the files listed in the `IMAGE_BOOT_FILES` variable.

▶ Creates an **ext4** partition with the contents on the root filesystem, excluding the content of `/home` and `/opt`

▶ Creates **two ext4** partitions, one with the content of `/home`, the other one with the content of `/opt`, from the image root filesystem.
Package groups
Overview

- Package groups are a way to group packages by functionality or common purpose.
- Package groups are used in image recipes to help building the list of packages to install.
- They can be found under `meta*/recipes-core/packagegroups/`
- A package group is yet another recipe.
  - Using the `packagegroup` class.
- The prefix `packagegroup-` is always used.
- Be careful about the `PACKAGE_ARCH` value:
  - Set to the value `all` by default,
  - Must be explicitly set to `${MACHINE_ARCH}` when there is a machine dependency.
Common package groups

- packagegroup-core-boot
- packagegroup-core-buildessential
- packagegroup-core-nfs-client
- packagegroup-core-nfs-server
- packagegroup-core-tools-debug
- packagegroup-core-tools-profile
Example

./meta/recipes-core/packagegroups/packagegroup-core-tools-debug.bb:

```plaintext
SUMMARY = "Debugging tools"

inherit packagegroup

RDEPENDS: @{$PN} = "\n     gdb \n     gdbserver \n     strace"
```
Practical lab - Create a custom image

- Write an image recipe
- Choose the packages to install
Writing recipes - going further
Writing recipes - going further

The per-recipe sysroot
The *sysroot* is the logical root directory for headers and libraries.

Where *gcc* looks for headers, and *ld* looks for libraries.

Contains:

- The kernel headers
- The C library and headers
- Other libraries and their headers
Per-recipe sysroot

▶ Instead of a global sysroot, bitbake implements a *per-recipe sysroot*
▶ Before the actual build, each recipe prepares its own sysroot
  • Contains libraries and headers *only* for the recipes it **DEPENDS** on
  • Ensures the configuration stage will not detect libraries not explicitly listed in **DEPENDS** but already built for other reasons
  • `${WORKDIR}/recipe-sysroot` for target recipes
  • `${WORKDIR}/recipe-sysroot-native` for native recipes
▶ At the end of the build, each recipe produces its destination sysroot
  • Its own slice of sysroot, with the libraries and headers it directly provides
  • Used as input for other recipes to generate their recipe-sysroot
  • `${WORKDIR}/sysroot-destdir`
Per-recipe sysroot

```
ncurses
```

```
do_install  do_populate_sysroot

do_prepare_recipe_sysroot  do_configure
```

```
${WORKDIR}  image/

sysroot-destdir/
```

```
${WORKDIR}

recipe-sysroot/
```
The complete sysroot

- A complete sysroot is available:
  - For each image
    - In `${WORKDIR}/recipe-sysroot` just like any recipe
  - In the SDK
    - Covered later
Using Python code in metadata
Tasks can be written in Python when using the `python` keyword.

Two modules are automatically imported:

- `bb`: to access BitBake’s internal functions.
- `os`: Python’s operating system interfaces.

You can import other modules using the `import` keyword.

Anonymous Python functions are executed during parsing.

Short Python code snippets can be written inline with the `@python code` syntax.
Accessing the datastore with Python

- The `d` variable is accessible within Python tasks.
- `d` represents the BitBake datastore (where variables are stored).

```python
# Get the value of X
d.getVar("X", expand=False)  # Returns the value of X.

# Set the value of X
d.setVar("X", "value")  # Set X.

# Append value to X
d.appendVar("X", "value")  # Append value to X.

# Prepend value to X
d.prependVar("X", "value")  # Prepend value to X.

# Expand variables in expression
d.expand(expression)  # Expand variables in expression.
```
# Anonymous function
```python
__anonymous() {
    if d.getVar("FOO", True) == "example":
        d.setVar("BAR", "Hello, World.")
}
```

# Task
```python
do_settime() {
    import time
    d.setVar("TIME", time.strftime('%Y%m%d', time.gmtime()))
}
```

# Inline
```python
do_install() {
    echo "Build OS: ${@os.uname()[0].lower()}"
}
```
Variable flags
Variable flags

- Variable flags, or varflags, are used to store extra information on tasks and variables.
- They are used to control task functionalities.
- A typical example:
  
  ```
  SRC_URI[md5sum] = "97b2c3fb082241ab5c56ab728522622b"
  ```
- See the list of varflags supported by Bitbake.
- More varflags can be added freely.
Examples

- **dirs**: directories that should be created before the task runs. The last one becomes the work directory for the task.
  
  ```
  do_compile[dirs] = "${B}"
  ```

- **noexec**: disable the execution of the task.
  
  ```
  do_settime[noexec] = "1"
  ```

- **nostamp**: do not create a *stamp* file when running the task. The task will always be executed.
  
  ```
  do_menuconfig[nostamp] = "1"
  ```

- **doc**: task documentation displayed by *listtasks*.
  
  ```
  do_settime[doc] = "Set the current time in ${TIME}"
  ```

- **depends**: add a dependency between specific tasks
  
  ```
  do_patch[depends] = "quilt-native:do_populate_sysroot"
  ```
Writing recipes - going further

Packages features
Benefits

- Features can be built depending on the needs.
- This allows to avoid compiling all features in a software component when only a few are required.
- A good example is ConnMan: Bluetooth support is built only if there is Bluetooth on the target.
- The `PACKAGECONFIG` variable is used to configure the build on a per feature granularity, for packages.
PACKAGECONFIG

- PACKAGECONFIG takes the list of features to enable.
- PACKAGECONFIG[feature] takes up to six arguments, separated by commas:
  1. Argument used by the configuration task if the feature is enabled (`EXTRA_OECONF`).
  2. Argument added to `EXTRA_OECONF` if the feature is disabled.
  3. Additional build dependency (`DEPENDS`), if enabled.
  4. Additional runtime dependency (`RDEPENDS`), if enabled.
  5. Additional runtime recommendations (`RRECOMMENDS`), if enabled.
  6. Any conflicting PACKAGECONFIG settings for this feature.

- Unused arguments can be omitted or left blank.
Example: from ConnMan

```bash
PACKAGECONFIG ??= "wifi openvpn"

PACKAGECONFIG[wifi] = "--enable-wifi, --disable-wifi, wpa-supplicant, wpa-supplicant"

PACKAGECONFIG[bluez] = "--enable-bluetooth, --disable-bluetooth, bluez5, bluez5"

PACKAGECONFIG[openvpn] = "--enable-openvpn, --disable-openvpn, , openvpn"
```
Enabling PACKAGECONFIG features

▶ In a .bbappend of the recipe, just append to PACKAGECONFIG

```
PACKAGECONFIG:append = " <feature>"
PACKAGECONFIG:append = " tui"
```

▶ In a config file (e.g. distro conf)

```
PACKAGECONFIG:append:pn-<recipename> = " <feature>"
PACKAGECONFIG:append:pn-gdb = " tui"
```
Inspecting available PACKAGECONFIG flags

>`${POKY_DIR}/scripts/contrib/list-packageconfig-flags.py` shows the PACKAGECONFIG `varflags` available for each recipe:

```bash
$ ../poky/scripts/contrib/list-packageconfig-flags.py
RECIPE NAME   PACKAGECONFIG FLAGS
==================================
alsa-plugins  aaf jack libav maemo-plugin maemo-resource-manager pulseaudio samplerate speexdsp
connman       3g bluez client iptables l2tp nfc nftables openvpn pptp systemd tist vpnc wifi ...
gdb          babeltrace debuginfo fod python readline tui xz
...            
```

The `-a` flag shows all the details:

```bash
$ ../poky/scripts/contrib/list-packageconfig-flags.py -a
connman-1.41
/home/murray/w/yocto-stm32-labs/poky/meta/recipes-connectivity/connman/connman_1.41.bb
PACKAGECONFIG wispr iptables client 3g wifi bluez
PACKAGECONFIG[wifi] --enable-wifi, --disable-wifi, wpa-supplicant, wpa-supplicant
PACKAGECONFIG[bluez] --enable-bluetooth, --disable-bluetooth, bluez5, bluez5
PACKAGECONFIG[openvpn] --enable-openvpn --with-openvpn=${sbindir}/openvpn,--disable-openvpn,,openvpn
```
Conditional features
Some values can be set dynamically, thanks to a set of functions:

- **bb.utils.contains(variable, checkval, trueval, falseval, d):** if `checkval` is found in `variable`, `trueval` is returned; otherwise `falseval` is used.
- **bb.utils.filter(variable, checkvalues, d):** returns all the words in the `variable` that are present in the `checkvalues`.

**Example:**

```
PACKAGECONFIG ??= "wispr iptables client\n $(@bb.utils.filter('DISTRO_FEATURES', '3g systemd wifi', d)) \n $(@bb.utils.contains('DISTRO_FEATURES', 'bluetooth', 'bluez', '', d)) \n"
```
Package splitting
do_install copies all files in the D directory ($WORKDIR/image).

do_package splits files in several packages in
$WORKDIR/packages-split

- based on the PACKAGES and FILES variables.

do_package_write_rpm generates RPM packages
PACKAGES

▶ **PACKAGES** lists the packages to be built:

```
PACKAGES = "${PN}-src ${PN}-dbg ${PN}-staticdev ${PN}-dev \n ${PN}-doc ${PN}-locale ${PACKAGE_BEFORE_PN} ${PN}"
```

▶ More packages can be added to the default list

- Useful when a single remote repository provides multiple binaries or libraries.
- The order matters. `PACKAGE_BEFORE_PN` allows to pick files normally included in the default package in another.

▶ **PACKAGES_DYNAMIC** allows to check dependencies with optional packages are satisfied.

▶ **ALLOWEMPTY** allows to produce a package even if it is empty.

▶ To prevent configuration files from being overwritten during the Package Management System update process, use **CONFFILES**.
For each package a FILES variable lists the files to include.

- It must be package specific (e.g. with :${PN}, :${PN}-dev, dots).

- Defaults from meta/conf/bitbake.conf:

```bash
FILES:${{PN}}-dev = \
"${{includedir}} ${{FILES_SOLIBSDEV}} ${{libdir}}/*.la \n${{libdir}}/*.o ${{libdir}}/pkgconfig ${{datadir}}/pkgconfig \n${{datadir}}/aclocal ${{base_libdir}}/*.o \n${{libdir}}/{{BPN}}/*.la ${{base_libdir}}/*.la \n${{libdir}}/cmake ${{datadir}}/cmake"
FILES:${{PN}}-dbg = \n"/usr/lib/debug /usr/lib/debug-static \n/usr/src/debug"
```
The package named just ${PN} is the one that gets installed in the root filesystem.

In Poky, defaults to:

```bash
FILES: ${PN} = 
"${bindir}/* ${sbindic}/* ${libexecdir}/* ${libdir}/lib*${SOLIBS} 
${sysconfdir} ${sharedstatedir} ${localstatedir} 
${base_bindir}/* ${base_sbindir}/* \n${base_libdir}/*${SOLIBS} \n${base_prefix}/lib/udev/rules.d ${prefix}/lib/udev/rules.d 
${datadir}/${BPN} ${libdir}/${BPN}/* \n${datadir}/pixmaps ${datadir}/application s 
${datadir}/idl ${datadir}/omf ${datadir}/sounds \n${libdir}/bonobo/servers"
```
The `kexec` tools provides `kexec` and `kdump`:

```plaintext
require kexec-tools.inc
export LDFLAGS = "-L${STAGING_LIBDIR}"
EXTRA_OECONF = " --with-zlib=yes"

SRC_URI[md5sum] = "b9f2a3ba0ba9c78625ee7a50532500d8"

PACKAGES += "kexec kdump"

FILES:kexec = "${bindir}/kexec"
FILES:kdump = "${{bindir}}/kdump"
```
Inspecting packages

`oe-pkgdata-util` is a tool that can help inspecting packages:

▶ Which package is shipping a file:

```
$ oe-pkgdata-util find-path /bin/busybox
busybox: /bin/busybox
```

▶ Which files are shipped by a package:

```
$ oe-pkgdata-util list-pkg-files busybox
busybox:
    /bin/busybox
    /bin/busybox.nosuid
    /bin/busybox.suid
    /bin/sh
```

▶ Which recipe is creating a package:

```
$ oe-pkgdata-util lookup-recipe kdump
ekexec-tools
$ oe-pkgdata-util lookup-recipe libtinfo5
ncurses
```
Dependencies in detail
DEPENDS describes a build-time dependency

Typical case: a program needs the library and headers files from a library to be configured and/or built

In other words: it needs the library in its `sysroot`

In `ninvaders.bb`, the line

```bash
DEPENDS = "ncurses"
```

creates a dependency

- Of `ninvaders.do_prepare_recipe_sysroot`
- On `ncurses.do_populate_sysroot`
RDEPENDS describes a runtime dependency

Typical case: a program uses another program at runtime via sockets, DBUS, etc, or simply executes it

It does not need it at build time

In `inetutils_2.4.bb`, the line

```bash
RDEPENDS:${PN}-ftpd += "xinethd"
```

creates a dependency

- Of `inetutils.do_build`
- On `xinethd.do_package_write_rpm`

And adds in the `inetutils-ftpd` RPM package a dependency on the `xinethd` RPM package
RRECOMMENDS is similar to RDEPENDS

But if the dependency package is not built it will just be skipped instead of failing the build

Typical cases:
- A package extends the features of a program, but its build has been disabled explicitly (e.g. via BAD_RECOMMENDATIONS)
- Depending on a kernel module that might also be built-in in the kernel Image

In watchdog_5.16.bb, the line

```bash
RRECOMMENDS:=${PN} += "kernel-module-softdog"
```

does nothing if the softdog kernel module is not built by the kernel (could be builtin)
Managing licenses
The license of an external project may change at some point. The `LIC_FILES_CHKSUM` tracks changes in the license files. If the license’s checksum changes, the build will fail.

- The recipe needs to be updated.

```
LIC_FILES_CHKSUM = "
  file://COPYING;md5=...
  file://src/file.c;beginline=3;endline=21;md5=..."
```

- `LIC_FILES_CHKSUM` is mandatory in every recipe, unless `LICENSE` is set to `CLOSED`. 

Package exclusion

- We may not want some packages due to their licenses.
- To exclude a specific license, use `INCOMPATIBLE_LICENSE`
- To exclude all GPLv3 packages:

  `INCOMPATIBLE_LICENSE = "GPL-3.0* LGPL-3.0* AGPL-3.0*"`

- License names are the ones used in the `LICENSE` variable.
Commercial licenses

- By default the build system does not include commercial components.
- Packages with a commercial component define:

```
LICENSE_FLAGS = "commercial"
```

- To build a package with a commercial component, the package must be in the LICENSE_FLAGS_ACCEPTED variable.
- Example, gst-plugins-ugly:

```
LICENSE_FLAGS_ACCEPTED = "commercial_gst-plugins-ugly"
```
Listing licenses

OpenEmbedded will generate a manifest of all the licenses of the software present on the target image in $BUILDDIR/tmp/deploy/licenses/<image>/license.manifest

<table>
<thead>
<tr>
<th>PACKAGE NAME</th>
<th>busybox</th>
<th>PACKAGE VERSION</th>
<th>1.31.1</th>
<th>RECIPE NAME</th>
<th>busybox</th>
<th>LICENSE</th>
</tr>
</thead>
<tbody>
<tr>
<td>PACKAGE NAME</td>
<td>dropbear</td>
<td>PACKAGE VERSION</td>
<td>2019.78</td>
<td>RECIPE NAME</td>
<td>dropbear</td>
<td>LICENSE</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>MIT &amp; BSD-3-Clause &amp; BSD-2-Clause &amp; PD</td>
</tr>
</tbody>
</table>

You can also include the manifest and individual licenses in the root filesystem:

- Either use `COPY_LIC_DIRS = "1"` and `COPY_LIC_MANIFEST = "1"`
- Or use `LICENSE_CREATE_PACKAGE = "1"` to generate and install packages including the license files.
Providing sources

OpenEmbedded provides the archiver class to generate tarballs of the source code, to meet the requirements of some licenses:

- Use INHERIT += "archiver"
- Set the ARCHIVER_MODE variable, the default is to provide patched sources. To provide configured sources:

```
ARCHIVER_MODE[src] = "configured"
```
Instead of generating license information and source tarballs separately, OpenEmbedded can actually generate an SBoM, describing:

- **Sources** for target and host components
- **Licenses** of such components
- **Dependencies** between such components
- **Applied changes**, in particular fixes for known vulnerabilities.

This SBoM is generated in the standard SPDX format, which you can feed to tools supporting SPDX.
SPDX SBoM can be attached to a software delivery, and used for:

- License compliance assessment
- Vulnerability assessment. You can use the SBoM to check whether your software supply chain is impacted by currently known vulnerabilities, both in host and target packages.

The US government is pushing for having such information in all software it procures and will probably make it mandatory soon.
How to create SPDX SBoM with OpenEmbedded

- Add `INHERIT += "create-spdx"` to your configuration file.
- JSON SPDX files will be generated in `tmp/deploy/images/MACHINE/`
- You can then set optional variables:
  - `SPDXPRETTY`: Make generated files more human readable (newlines, indentation)
  - `SPDX_ARCHIVE_PACKAGED`: Add compressed archives of the files in generated target packages.
  - `SPDXINCLUDE_SOURCES`: Add descriptions of the source files for host tools and target packages.
  - `SPDX_ARCHIVE_SOURCES`: Add archives of these source files themselves (when `SPDXINCLUDE_SOURCES` is set).
Example IMAGE-MACHINE.spdx.json output

```
{
  "SPDXID": "SPDXRef-DOCUMENT",
  "creationInfo": {
    "comment": "This document was created by analyzing the source of the Yocto recipe during the build.",
    "created": "2022-10-25T12:32:13Z",
    "creators": [
      "Tool: OpenEmbedded Core create-spdx.bbclass",
      "Organization: OpenEmbedded ()",
      "Person: N/A ()"
    ],
    "licenseListVersion": "3.14"
  },
  "dataLicense": "CC0-1.0",
  "documentNamespace": "http://spdx.org/spdxdoc/core-image-minimal-qemux86-64-20221025122556-f686f4f3-...",
  "externalDocumentRefs": [
    {
      "checksum": {
        "algorithm": "SHA1",
        "checksumValue": "f6de08ea7fa026f480fd80cf7862a5c99c4d7a2b"
      },
      "externalDocumentId": "DocumentRef-base-files",
      "spdxDocument": "http://spdx.org/spdxdoc/base-files-ee9424e3-1d7e-5739-b9cd-237a1a6f843f"
    }
  ],
  ...
}
```

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Further resources about SPDX SBoM

▶ Yocto project documentation:
https://docs.yoctoproject.org/dev/dev-manual/sbom.html

▶ Joshua Watt: Automated SBoM generation with OpenEmbedded and the Yocto Project (FOSDEM 2023)
https://youtu.be/Q5UQUM6zxVU

▶ SPDX project homepage:
https://spdx.dev
An SDK (Software Development Kit) is a set of tools allowing the development of applications for a given target (operating system, platform, environment, ...).

It generally provides a set of tools including:

- Compilers or cross-compilers.
- Linkers.
- Library headers.
- Debuggers.
- Custom utilities.
The Poky reference system is used to generate images, by building many applications and doing a lot of configuration work.

- When developing an application, we only care about the application itself.
- We want to be able to develop, test and debug easily.

The Yocto Project SDK is an application development SDK, which can be generated to provide a full environment compatible with the target.

- It includes a toolchain, libraries headers and all the needed tools.
- This SDK can be installed on any computer and is self-contained. The presence of Poky is not required for the SDK to fully work.
Available SDKs

- Two different SDKs can be generated:
  - A generic SDK, including:
    - A toolchain.
    - Common tools.
    - A collection of basic libraries.
  - An image-based SDK, including:
    - The generic SDK.
    - The sysroot matching the target root filesystem.

- The toolchain in the SDKs is self-contained (linked to an SDK embedded libc).
- The SDKs generated with Poky are distributed in the form of a shell script.
- Executing this script extracts the tools and sets up the environment.
The generic SDK

Mainly used for low-level development, where only the toolchain is needed:

- Bootloader development.
- Kernel development.

The recipe `meta-toolchain` generates this SDK:

- `bitbake meta-toolchain`

The generated script, containing all the tools for this SDK, is in:

- `$BUILDDIR/tmp/deploy/sdk`

  Example:
  `poky-glibc-x86_64-meta-toolchain-cortexa8hf-neon-toolchain-2.5.sh`

The SDK will be configured to be compatible with the specified `MACHINE`. 
The image-based SDK

- Used to develop applications running on the target.
- One task is dedicated to the process. The task behavior can vary between the images.
  - populate_sdk
- To generate an SDK for `core-image-minimal`:
  - `bitbake -c populate_sdk core-image-minimal`
- The generated script, containing all the tools for this SDK, is in:
  - `$BUILDDIR/tmp/deploy/sdk`
  - Example:
    - `poky-glibc-x86_64-core-image-minimal-cortexa8hf-neon-toolchain-2.5.sh`
- The SDK will be configured to be compatible with the specified `MACHINE`. 
Adding packages to the SDK

▶ Two variables control what will be installed in the SDK

TOOLCHAIN_TARGET_TASK  List of target packages to be included in the SDK

TOOLCHAIN_HOST_TASK  List of host packages to be included in the SDK

▶ Both can be appended to install more tools or libraries useful for development.
▶ Example: to have native curl on the SDK:

TOOLCHAIN_HOST_TASK:append = "nativesdk-curl"
Both SDKs are distributed as bash scripts.

These scripts self extract themselves to install the toolchains and the files they provide.

To install an SDK, retrieve the generated script and execute it.

- The script asks where to install the SDK. Defaults to /opt/poky/<version>
- Example: /opt/poky/2.5

```
$ ./poky-glibc-x86_64-meta-toolchain-cortexa8hf-neon-toolchain-2.5.sh
Poky (Yocto Project Reference Distro) SDK installer version 2.5
===============================================================================
Enter target directory for SDK (default: /opt/poky/2.5):
You are about to install the SDK to "/opt/poky/2.5". Proceed[Y/n]?
Extracting SDK.................done
Setting it up...done
SDK has been successfully set up and is ready to be used.
Each time you wish to use the SDK in a new shell session, you need to source the environment setup script e.g.
$ . /opt/poky/2.5/environment-setup-cortexa8hf-neon-poky-linux-gnueabi
```
To use the SDK, a script is available to set up the environment:

```bash
$ cd /opt/poky/2.5
$ source ./environment-setup-cortexa8hf-neon-poky-linux-gnueabi
```

- The PATH is updated to take into account the binaries installed alongside the SDK.
- Environment variables are exported to help using the tools.
SDK installation

- **environment-setup-cortexa8hf-neon-poky-linux-gnueabi** Exports environment variables.
- **site-config-cortexa8hf-neon-poky-linux-gnueabi** Variables used during the toolchain creation
- **sysroots** SDK binaries, headers and libraries. Contains one directory for the host and one for the target.
- **version-cortexa8hf-neon-poky-linux-gnueabi** Version information.
SDK environment variables

CC    Full path to the C compiler binary.
CFLAGS C flags, used by the C compiler.
CXX   C++ compiler.
CXXFLAGS C++ flags, used by CPP
LD    Linker.
LDFLAGS Link flags, used by the linker.
ARCH  For kernel compilation.
CROSS_COMPILE For kernel compilation.
GDB   SDK GNU Debugger.
OBJDUMP SDK objdump.

▶ To see the full list, open the environment script.
Examples

▶ To build an application for the target:

$ $CC -o example example.c

▶ The LDFLAGS variables is set to be used with the C compiler (gcc).
  • When building the Linux kernel, unset this variable.

$ unset LDFLAGS
$ make menuconfig
$ make
Generate an SDK

Compile an application for the target in the SDK
Overview

▶ Devtool is a set of utilities to ease the integration and the development of OpenEmbedded recipes.

▶ It can be used to:
  - Generate a recipe for a given upstream application.
  - Modify an existing recipe and its associated sources.
  - Upgrade an existing recipe to use a newer upstream application.

▶ Devtool adds a new layer, automatically managed, in $BUILDDIR/workspace/.

▶ It then adds or appends recipes to this layer so that the recipes point to a local path for their sources. In $BUILDDIR/workspace/sources/.
  - Local sources are managed by git.
  - All modifications made locally should be committed.
There are three ways of creating a new devtool project:

▶ To create a new recipe: `devtool add <recipe> <fetchuri>`
  - Where `recipe` is the recipe’s name.
  - `fetchuri` can be a local path or a remote `uri`.

▶ To modify the source for an existing recipe: `devtool modify <recipe>`

▶ To upgrade a given recipe: `devtool upgrade -V <version> <recipe>`
  - Where `version` is the new version of the upstream application.
Once a devtool project is started, commands can be issued:

- `devtool edit-recipe <recipe>`: edit recipe in a text editor (as defined by the EDITOR environment variable).
- `devtool build <recipe>`: build the given recipe.
- `devtool build-image <image>`: build image with the additional devtool recipes’ packages.
devtool usage 3/3

- devtool deploy-target <recipe> <target>: upload the recipe’s packages on target, which is a live running target with an SSH server running (user@address).
- devtool update-recipe <recipe>: generate patches from git commits made locally.
- devtool reset <recipe>: remove recipe from the control of devtool. Standard layers and remote sources are used again as usual.
Automating layer management
Release management

There are multiple tasks that OE/bitbake based projects let you do on your own to ensure build reproducibility:

- Code distribution and project setup.
- Release tagging

A separate tool is needed for that, usual solutions are:

- git submodules + setup script. Great example in YOE: https://github.com/YoeDistro/yoe-distro
- repo and templateconf or setup script
- kas
A good way to distribute a distribution (Poky, custom layers, BSP, .templateconf...) is to use Google’s repo.

Repo is used in Android to distribute its source code, which is split into many git repositories. It’s a wrapper to handle several git repositories at once.

The only requirement is to use git.

The repo configuration is stored in manifest file, usually available in its own git repository.

It could also be in a specific branch of your custom layer.

It only handles fetching code, handling local.conf and bblayers.conf is done separately.
<?xml version="1.0" encoding="UTF-8"?>
<manifest>
    <remote name="yocto-project" fetch="git.yoctoproject.org"/>
    <remote name="private" fetch="git.example.net"/>

    <default revision="kirkstone" remote="private"/>

    <project name="poky" remote="yocto-project"/>
    <project name="meta-ti" remote="yocto-project"/>
    <project name="meta-custom"/>
    <project name="meta-custom-bsp"/>
    <project path="meta-custom-distro" name="distro">
        <copyfile src="templateconf" dest="poky/.templateconf"/>
    </project>
</manifest>
Retrieve the project using `repo`

```bash
$ mkdir my-project; cd my-project
$ repo init -u https://git.example.net/manifest.git
$ repo sync -j4
```

- `repo init` uses the `default.xml` manifest in the repository, unless specified otherwise.
- You can see the full `repo` documentation at [https://source.android.com/source/using-repo.html](https://source.android.com/source/using-repo.html).
To tag a release, a few steps have to be taken:

- Optionally tag the custom layers
- For each project entry in the manifest, set the revision parameter to either a tag or a commit hash.
- Commit and tag this version of the manifest.
Specific tool developed by Siemens for OpenEmbedded: https://github.com/siemens/kas
- Will fetch layers and build the image in a single command
- Uses a single JSON or YAML configuration file part of the custom layer
- Can generate and run inside a Docker container
- Can setup `local.conf` and `bblayers.conf`
header:
  version: 8
machine: mymachine
distro: mydistro
target:
  - myimage
repos:
  meta-custom:
    bitbake:
      url: "https://git.openembedded.org/bitbake"
      refspec: "2.0"
      layers:
        .: excluded
    openembedded-core:
      url: "https://git.openembedded.org/openembedded-core"
      refspec: kirkstone
      layers:
        meta:
kas configuration

meta-freescale:
  url: "https://github.com/Freescale/meta-freescale"
  refspec: kirkstone

meta-openembedded:
  url: https://git.openembedded.org/meta-openembedded
  refspec: kirkstone
  layers:
    meta-oe:
    meta-python:
    meta-networking:

▶ Then a single command will build all the listed target for the machine:

$ kas build meta-custom/mymachine.yaml

▶ Or, alternatively, invoke bitbake commands:

$ kas shell /path/to/kas-project.yml -c 'bitbake dosfsutils-native'
Runtime Package Management
BitBake always builds packages selected in IMAGE_INSTALL.

The packages are used to generate the root filesystem.

It is also possible to update the system at runtime using these packages, for many use cases:

- In-field security updates.
- System updates over the wire.
- System, packages or configuration customization at runtime.
- Remote debugging.

Using the Runtime Package Management is an optional feature.

We’ll use the IPK package format as an example in the following slides.
First of all, you need a server to serve the packages to a private subnet or over the Internet. Packages are typically served over `https` or `http`.

Specific tools are also required on the target, and must be shipped on the product. They should be included into the images generated by the build system.

These tools will be specific to the package type used.

- This is similar to Linux distributions: Debian is using `.deb` related tools (`dpkg`, `apt`...) while Fedora uses `.rpm` related ones (`rpm`, `dnf`).
Build configuration
The `PACKAGE_CLASSES` variable controls which package format to use. More than one can be used.

Valid values are `package_rpm`, `package_deb`, `package_ipk`.

By default Poky uses the RPM format, while OpenEmbedded-Core uses the IPK one.

Example:
- `PACKAGE_CLASSES = "package_ipk"
- `PACKAGE_CLASSES = "package_rpm package_deb"`
To install the required tools on the target, there are two possible solutions:

- **By adding `package-management` to the images features.**
  - The required tool will be installed on the target.
  - The package database corresponding to the build will be installed as well.

- **Or by manually adding the required tools in `IMAGE_INSTALL`.** For example, to use the IPK format we need `opkg`. 
Build considerations

- The Runtime Package Management uses package databases to store information about available packages and their version.
- Whenever a build generates a new package or modifies an existing one, the package database must be updated.
- `$ bitbake package-index`
- Be careful: BitBake does not properly schedule the `package-index` target. You must use this target alone to have a consistent package database.
  - `$ bitbake ninvaders package-index` won't necessarily generate an updated package database.
Package server configuration
Apache2 example setup

Apache2 HTTP setup for IPK packages. This should go in /etc/apache2/sites-enabled/package-server.conf.

```xml
<VirtualHost *:80>
    ServerName packages.example.net

    DocumentRoot /path/to/build/tmp/deploy/ipk
    <Directory /path/to/build/tmp/deploy/ipk>
        Options +Indexes
        Options Indexes FollowSymLinks
        Order allow,deny
        allow from all
        AllowOverride None
        Require all granted
    </Directory>
</VirtualHost>
```
Target configuration
The IPK runtime management software

- The IPK runtime management software is opkg.
- It can be configured using configurations files ending in .conf in /etc/opkg/.
- This configuration helps opkg to find the package databases you want to use.
- For example, with our previously configured package server:

```
src/gz all http://packages.example.net/all
src/gz armv7a http://packages.example.net/armv7a
src/gz beaglebone http://packages.example.net/beaglebone
```

- This can be automatically generated by defining the PACKAGE_FEED URIS, PACKAGE_FEED_BASE_PATHS and PACKAGE_FEED_ARCHS variables.
opkg usage

- **opkg update**: fetch and update the package databases, from the remote package servers.
- **opkg list**: list available packages.
- **opkg upgrade**: upgrade all installed packages.
- **opkg upgrade <package>**: upgrade one package explicitly.
- **opkg install <package>**: install a specific package.
To avoid upgrade issues when downloading packages from a remote package server using an unstable connection, you can first download the packages and then proceed with the upgrade.

To do this we must use a cache, which can be defined in the `opkg` configuration with: `option cache /tmp/opkg-cache`.

```
# opkg update
# opkg --download-only upgrade
# opkg upgrade
```
Yocto Project documentation

- https://docs.yoctoproject.org/
- Wiki: https://wiki.yoctoproject.org/wiki/Main_Page
- https://layers.openembedded.org/
Embedded Linux Development Using Yocto Project - Third Edition, April 2023

- By Daiane Angolini and Otavio Salvador
- From basic to advanced usage, helps writing better, more flexible recipes. A good reference to jumpstart your Yocto Project development.
Embedded Linux Projects Using Yocto Project Cookbook - Second Edition, January 2018

- By Alex González
- A set of recipes that you can refer to and solve your immediate problems instead of reading it from cover to cover.

See our review: [https://bit.ly/1GgVmCB](https://bit.ly/1GgVmCB)
Last slides
Thank you!
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**Document sources:** https://github.com/bootlin/training-materials/
Extra slides
Quilt
Quilt is a utility to manage patches which can be used without having a clean source tree.

It can be used to create patches for recipes already available in the build system.

Be careful when using this workflow: the modifications won’t persist across builds!
1. Find the recipe working directory in $BUILDDIR/tmp/work/.
2. Create a new Quilt patch: $ quilt new topic.patch
3. Add files to this patch: $ quilt add file0.c file1.c
4. Make the modifications by editing the files.
5. Test the modifications: $ bitbake -c compile -f recipe
6. Generate the patch file: $ quilt refresh
7. Move the generated patch into the recipe’s directory.