



Real-Time Linux with *PREEMPT_RT* training

On-site training, 2 days

Latest update: December 06, 2021

Title	Real-Time Linux with <i>PREEMPT_RT</i> training
Training objectives	<ul style="list-style-type: none">• Be able to understand the characteristics of a real-time operating system• Be able to download, build and use the <i>PREEMPT_RT</i> patch• Be able to identify and benchmark the hardware platform in terms of real-time characteristics• Be able to configure the Linux kernel for deterministic behavior.• Be able to develop, trace and debug real-time user-space Linux applications.
Duration	Two days - 16 hours (8 hours per day).
Pedagogics	<ul style="list-style-type: none">• Lectures delivered by the trainer: 50% of the duration• Practical labs done by participants: 50% of the duration• Electronic copies of presentations, lab instructions and data files. They are freely available at bootlin.com/doc/training/preempt-rt.
Trainer	Maxime Chevallier https://bootlin.com/company/staff/maxime-chevallier/
Language	Oral lectures: English Materials: English.
Audience	Companies and engineers interested in writing and benchmarking real-time applications and drivers on an embedded Linux system.
Prerequisites	<ul style="list-style-type: none">• Knowledge and practice of UNIX or GNU/Linux commands: participants must be familiar with the Linux command line. Participants lacking experience on this topic should get trained by themselves, for example with our freely available on-line slides at bootlin.com/blog/command-line/.• Minimal experience in embedded Linux development: participants should have a minimal understanding of the architecture of embedded Linux systems: role of the Linux kernel vs. user-space, development of Linux user-space applications in C. Following Bootlin's <i>Embedded Linux</i> course at bootlin.com/training/embedded-linux/ allows to fulfill this pre-requisite.• Minimal English language level: B1, according to the <i>Common European Framework of References for Languages</i>, for our sessions in English. See bootlin.com/pub/training/cefr-grid.pdf for self-evaluation.

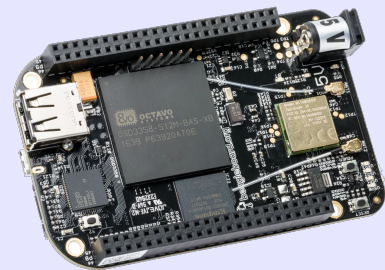


Required equipment	For on-site sessions at our customer location, the customer must provide: <ul style="list-style-type: none">• Video projector• One PC computer on each desk (for one or two persons) with at least 8 GB of RAM, and Ubuntu Linux 20.04 installed in a free partition of at least 30 GB• Distributions others than Ubuntu Linux 20.04 are not supported, and using Linux in a virtual machine is not supported.• Unfiltered and fast connection to Internet: at least 50 Mbit/s of download bandwidth, and no filtering of web sites or protocols.• PC computers with valuable data must be backed up before being used in our sessions.
Certificate	Only the participants who have attended all training sessions, and who have scored over 50% of correct answers at the final evaluation will receive a training certificate from Bootlin.
Disabilities	Participants with disabilities who have special needs are invited to contact us at training@bootlin.com to discuss adaptations to the training course.

Hardware in practical labs

The hardware platform used for the practical labs of this training session is the **BeagleBone Black** board, which features:

- An ARM AM335x processor from Texas Instruments (Cortex-A8 based), 3D acceleration, etc.
- 512 MB of RAM
- 2-4 GB of on-board eMMC storage
- USB host and device
- HDMI output
- 2 x 46 pins headers, to access UARTs, SPI buses, I2C buses and more.





Day 1

Lecture - Introduction to Real-Time behaviour and determinism

- Definition of a Real-Time Operating System
- Specificities of multi-task systems
- Common locking and prioritizing patterns
- Overview of existing Real-Time Operating Systems
- Approaches to bring Real-Time capabilities to Linux

Lecture - The *PREEMPT_RT* patch

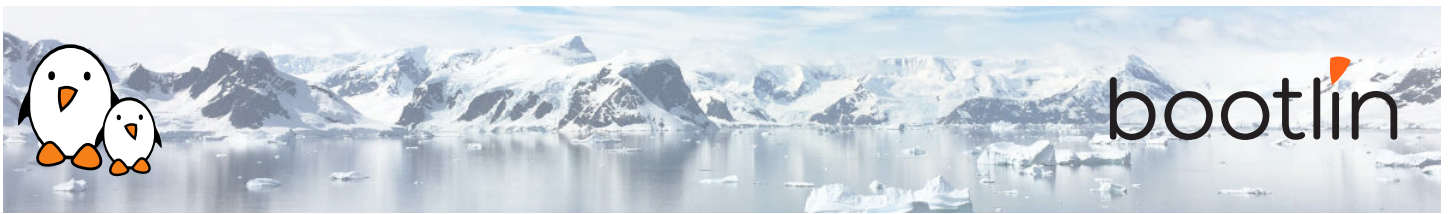
- History and future of the *PREEMPT_RT* patch
- Real-Time improvements from *PREEMPT_RT* in mainline Linux
- The internals of *PREEMPT_RT*
- Interrupt handling: threaded interrupts, softirqs
- Locking primitives: mutexes and spinlocks, sleeping spinlocks
- Preemption models

Lab - Building a mainline Linux Kernel with the *PREEMPT_RT* patch

- Downloading the Linux Kernel, and applying the patch
- Configuring the Kernel
- Booting the Kernel on a BeagleBone Black

Lecture - Hardware configuration and limitations for Real-Time

- Interrupts and deep firmwares
- Interaction with power management features: CPU frequency scaling and sleep states
- DMA



Lecture - Tools: Benchmarking, Stressing and Analyzing

- Benchmarking with *cyclicttest*
- System stressing with *stress-ng* and *hackbench*
- The Linux Kernel tracing infrastructure
- Latency and scheduling analysis with *ftrace*, *kernelshark* or *LTTng*

Lab - Tools: Benchmarking, Stressing and Analyzing

- Usage of benchmarking and stress tools
- Common benchmarking techniques
- Benchmarking and configuring the BeagleBone Black Wireless

Day 2

Lecture - Kernel infrastructures and configuration

- Good practices when writing Linux kernel drivers
- Scheduling policies and priorities: *SCHED_FIFO*, *SCHED_RR*, *SCHED_DEADLINE*
- CPU and IRQ Affinity
- Memory management
- CPU isolation with *isolcpus*

Lecture - Real-Time Applications programming patterns

- POSIX real-time API
- Thread management and configuration
- Memory management: memory allocation and memory locking, stack
- Locking patterns: mutexes, priority inheritance
- Inter-Process Communication
- Signaling

Lab - Debugging a demo application

- Make a demo userspace application deterministic
- Use the tracing infrastructure to identify the cause of a latency
- Learn how to use the POSIX API to manage threads, locking and memory
- Learn how to use the CPU affinities and configure the scheduling policy



Questions and Answers

- Questions and answers with the audience about the course topics
- Extra presentations if time is left, according what most participants are interested in.